

FS6500, FS4500: ASIL B

Safety power system basis chip with CAN FD and LIN transceivers

Rev. 3 — 14 April 2021

Product short data sheet

1 General description

The FS6500/FS4500 SMARTMOS devices are a multi-output, power supply, integrated circuit, including CAN Flexible Data (FD) and/or LIN transceivers, dedicated to the automotive market.

Multiple switching and linear voltage regulators, including low-power mode (32 μ A) are available with various wake-up capabilities. An advanced power management scheme is implemented to maintain high efficiency over a wide range of input voltages (down to 2.7 V) and output current ranges (up to 2.2 A).

The FS6500/FS4500 includes configurable fail-safe/fail silent safety behavior and features, with two fail-safe outputs, becoming a full part of a safety oriented system partitioning, to reach a high integrity safety level (up to ASIL B).

The built-in CAN FD interface fulfills the ISO 11898- $2^{(12)}$ and $-5^{(13)}$ standards. The LIN interface fulfills LIN protocol specifications 2.0, $2.1^{(22)}$, $2.2^{(23)}$, and SAE J2602- $2^{(24)}$.

High temperature capability up to T_A = 125 °C and T_J = 150 °C, compliant with AEC-Q100 Grade 1 automotive qualification.

2 Features and benefits

- Battery voltage sensing and MUX output pin
- Highly flexible SMPS pre-regulator, allowing two topologies: non-inverting buck-boost and standard buck
- Family of devices to supply MCU core from 1.0 V to 5.0 V, with SMPS (0.8 A, 1.5 A or 2.2 A) or LDO (0.5 A)
- Linear voltage regulator dedicated to auxiliary functions, or to sensor supply (V_{CCA} tracker or independent), 5.0 V, or 3.3 V
- Linear voltage regulator dedicated to MCU Analog/Digital (A/D) reference voltage or I/Os supply (V_{CCA}), 5.0 V, or 3.3 V
- 3.3 V keep alive memory supply available in low-power mode
- Long duration timer, counting up to 6 months with 1.0 s resolution
- Multiple wake-up sources in low-power mode: CAN, LIN, IOs, LDT
- Five configurable I/Os

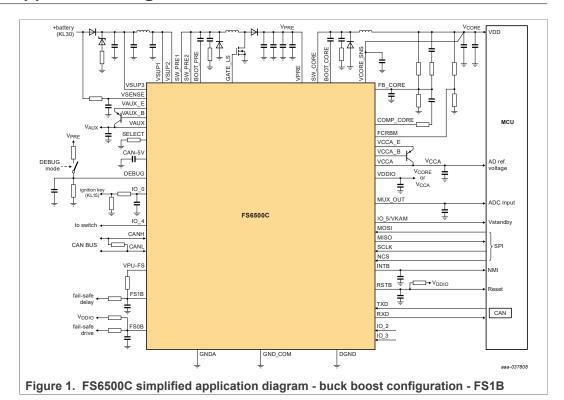
3 Applications

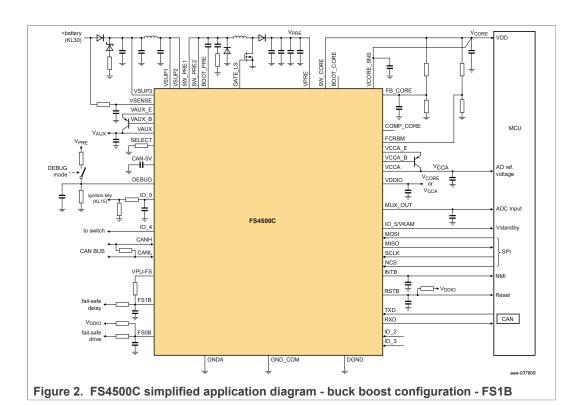
- Drive Train Electrification (BMS, Hybrid EV and HEV, Inverter, DC-DC, Alterno Starter)
- Drive Train Chassis and Safety (Active Suspension, Steering, Safety Domain Gateway)
- Power Train (EMS, TCU, Gear Box)
- ADAS (LDW, Radar, Sensor Fusion Safety area)



- On board charger
- Motor control

4 Simplified application diagrams





5 Ordering information

5.1 Part number definition

MC33FS <u>c</u> 5 <u>x</u> <u>y</u> <u>z</u> AE/R2

Table 1. Part number breakdown

| Code | Option | Variable | Description |
|------|----------|---------------------------|----------------|
| С | 4 series | V _{CORE} type | Linear |
| | 6 series | V CORE Type | DC-DC |
| x | 0 | | 0.5 A or 0.8 A |
| | 1 | V _{CORE} current | 1.5 A |
| | 2 | | 2.2 A |
| у | 5 | | None |
| | 6 | Functions | FS1B |
| | 7 | Functions | LDT |
| | 8 | | FS1B and LDT |
| Z | N | | None |
| | С | Physical interface | CAN FD |
| | К | Filysical illellace | LIN only |
| | L | | CAN FD and LIN |

5.2 Part numbers list

Table 2. Orderable part variations

| Part Number | Temperature (T _A) | Package | FS1B | LDT | VCORE | VCORE type | VKAM On | CAN FD | LIN | ASIL | Note |
|---------------|---|-------------|------|-------|-------|---------------|---------|-----------|-----|------|----------|
| MC33FS4505NAE | | | 0 | 0 | 0.5 A | Linear | by SPI | 0 | 0 | В | |
| MC33FS4505CAE | | | 0 | 0 | 0.5 A | Linear | by SPI | 1 | 0 | В | |
| MC33FS4505KAE | | | 0 | 0 | 0.5 A | Linear | By SPI | 0 | 1 | В | |
| MC33FS4505LAE | | | 0 | 0 | 0.5 A | Linear | By SPI | 1 | 1 | В | |
| MC33FS4506NAE | | | 1 | 0 | 0.5 A | Linear | by SPI | 0 | 0 | В | |
| MC33FS4506CAE | - | | 1 | 0 | 0.5 A | Linear | by SPI | 1 | 0 | В | |
| MC33FS4507NAE | | | 0 | 1 | 0.5 A | Linear | by SPI | 0 | 0 | В | |
| MC33FS4507CAE | - | | 0 | 1 | 0.5 A | Linear | by SPI | 1 | 0 | В | |
| MC33FS4507KAE | - | | 0 | 1 | 0.5 A | Linear | by SPI | 0 | 1 | В | |
| MC33FS4507LAE | - | | 0 | 1 | 0.5 A | Linear | by SPI | 1 | 1 | В | |
| MC33FS4508NAE | - | | 1 | 1 | 0.5 A | Linear | by SPI | 0 | 0 | В | |
| MC33FS4508CAE | | | 1 | 1 | 0.5 A | Linear | by SPI | 1 | 0 | В | |
| MC33FS6505NAE | - | | 0 | 0 | 0.8 A | DC-DC | by SPI | 0 | 0 | В | |
| MC33FS6505CAE | - | | 0 | 0 | 0.8 A | DC-DC | by SPI | 1 | 0 | В | |
| MC33FS6505KAE | - | | 0 | 0 | 0.8 A | DC-DC | by SPI | 0 | 1 | В | |
| MC33FS6505LAE | | | 0 | 0 | 0.8 A | DC-DC | by SPI | 1 | 1 | В | |
| MC33FS6506NAE | - | | 1 | 0 | 0.8 A | DC-DC | by SPI | 0 | 0 | В | |
| MC33FS6506CAE | - | | 1 | 0 | 0.8 A | DC-DC | by SPI | 1 | 0 | В | |
| MC33FS6507NAE | -40 °C to 125 °C 48-pin LQ exposed pad | 48-pin LQFP | 0 | 1 | 0.8 A | DC-DC | by SPI | 0 | 0 | В | [|
| MC33FS6507CAE | | | 0 | 1 | 0.8 A | DC-DC | by SPI | 1 | 0 | В | ' |
| MC33FS6507KAE | _ | F | 0 | 1 | 0.8 A | DC-DC | by SPI | 0 | 1 | В | |
| MC33FS6507LAE | _ | | 0 | 1 | 0.8 A | DC-DC | by SPI | 1 | 1 | В | |
| MC33FS6508NAE | _ | | 1 | 1 | 0.8 A | DC-DC | by SPI | 0 | 0 | В | |
| MC33FS6508CAE | _ | | 1 | 1 | 0.8 A | DC-DC | by SPI | 1 | 0 | В | |
| MC33FS6515NAE | | 0 | 0 | 1.5 A | DC-DC | by SPI | 0 | 0 | В | | |
| MC33FS6515CAE | | | 0 | 0 | 1.5 A | DC-DC | by SPI | 1 | 0 | В | |
| MC33FS6515KAE | | | 0 | 0 | 1.5 A | DC-DC | by SPI | 0 | 1 | В | |
| MC33FS6515LAE | | | 0 | 0 | 1.5 A | DC-DC | by SPI | 1 | 1 | В | |
| MC33FS6516NAE | | | 1 | 0 | 1.5 A | DC-DC | by SPI | 0 | 0 | В | |
| MC33FS6516CAE | | | 1 | 0 | 1.5 A | DC-DC | by SPI | 1 | 0 | В | |
| MC33FS6517NAE | | | 0 | 1 | 1.5 A | DC-DC | by SPI | 0 | 0 | В | |
| MC33FS6517CAE | | | 0 | 1 | 1.5 A | DC-DC | by SPI | 1 | 0 | В | |
| MC33FS6517KAE | | | 0 | 1 | 1.5 A | DC-DC | by SPI | 0 | 1 | В | |
| MC33FS6517LAE | | | 0 | 1 | 1.5 A | DC-DC | by SPI | 1 | 1 | В | |
| MC33FS6518NAE | _ | | 1 | 1 | 1.5 A | DC-DC | by SPI | 0 | 0 | В | |
| MC33FS6518CAE | | | 1 | 1 | 1.5 A | DC-DC | by SPI | 1 | 0 | В | |
| MC33FS6525NAE | - | | 0 | 0 | 2.2 A | DC-DC | by SPI | 0 | 0 | В | |
| MC33FS6525CAE | | | 0 | 0 | 2.2 A | DC-DC | by SPI | 1 | 0 | В | |

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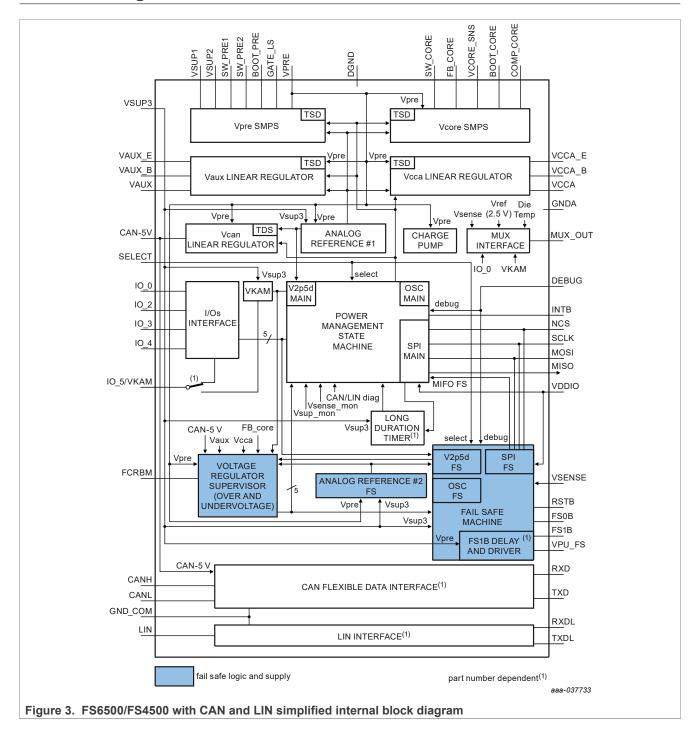
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Table 2. Orderable part variations...continued

| Part Number | Temperature (T _A) | Package | FS1B | LDT | VCORE | VCORE type | VKAM On | CAN FD | LIN | ASIL | Notes |
|---------------|----------------------------------|---------|------|-----|-------|---------------|---------|-----------|-----|------|-------|
| MC33FS6525KAE | | | 0 | 0 | 2.2 A | DC-DC | by SPI | 0 | 1 | В | |
| MC33FS6525LAE | | | 0 | 0 | 2.2 A | DC-DC | by SPI | 1 | 1 | В | |
| MC33FS6526NAE | | | 1 | 0 | 2.2 A | DC-DC | by SPI | 0 | 0 | В | |
| MC33FS6526CAE | | | 1 | 0 | 2.2 A | DC-DC | by SPI | 1 | 0 | В | |
| MC33FS6527NAE | | | 0 | 1 | 2.2 A | DC-DC | by SPI | 0 | 0 | В | |
| MC33FS6527CAE | | | 0 | 1 | 2.2 A | DC-DC | by SPI | 1 | 0 | В | |
| MC33FS6527KAE | | | 0 | 1 | 2.2 A | DC-DC | by SPI | 0 | 1 | В | |
| MC33FS6527LAE | | | 0 | 1 | 2.2 A | DC-DC | by SPI | 1 | 1 | В | |
| MC33FS6528NAE | | | 1 | 1 | 2.2 A | DC-DC | by SPI | 0 | 0 | В | |
| MC33FS6528CAE | | | 1 | 1 | 2.2 A | DC-DC | by SPI | 1 | 0 | В | |

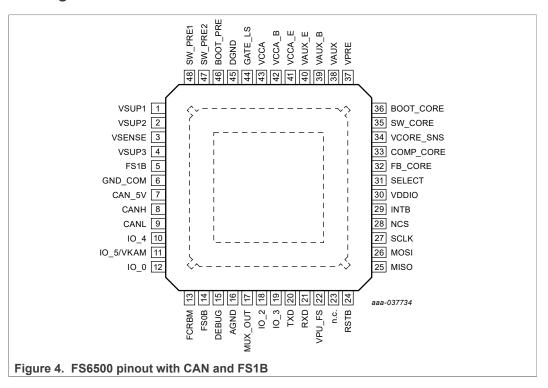
^[1] To order parts in tape and reel, add the R2 suffix to the part number.

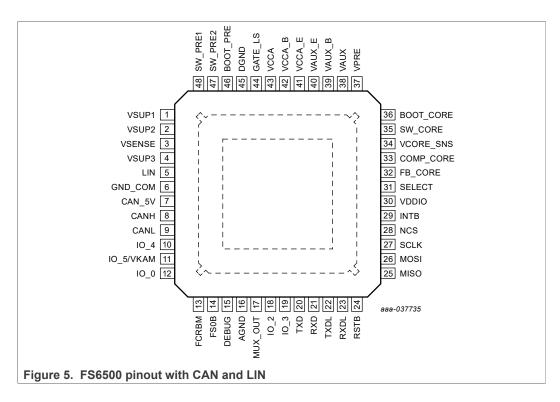
6 Block diagram

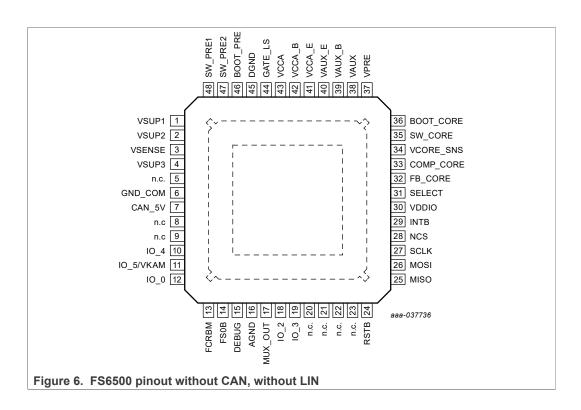


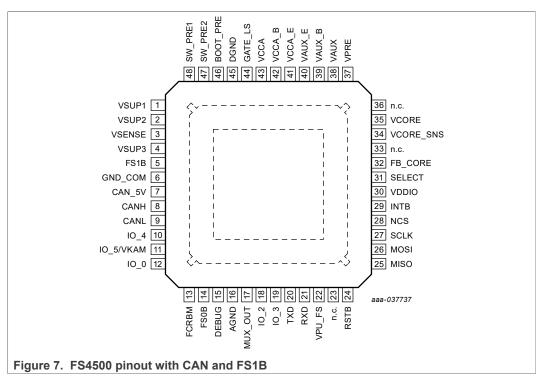
7 Pinning information

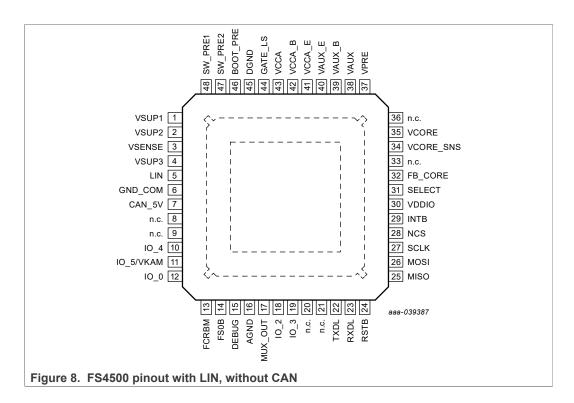
7.1 Pinning information











7.2 Pin description

A functional description of each pin can be found in the full data sheet.

Table 3. FS6500/FS4500 pin definition

| Pin number | Pin name | Туре | Definition |
|---------------|----------|----------|--|
| 1 | VSUP1 | A_IN | Power supply of the device. An external reverse battery protection diode in series is mandatory |
| 2 | VSUP2 | A_IN | Second power supply. Protected by the external reverse battery protection diode used for VSUP1. VSUP1 and VSUP2 must be connected together externally. |
| 3 | VSENSE | A_IN | Sensing of the battery voltage. Must be connected prior to the reverse battery protection diode. |
| 4 | VSUP3 | A_IN | Third power supply dedicated to the device supply. Protected by the external reverse battery protection diode used for VSUP1. Must be connected between the reverse protection diode and the input PI filter. |
| 5 | LIN | A_IN/OUT | LIN single-wire bus transmitter and receiver. |
| | or FS1B | D_OUT | Second output of the safety block (active low). The pin is asserted low at start-up and when a fault condition is detected, with a configurable delay or duration versus FS0B output terminal. Open drain structure. |
| | | | exclusive. The differentiation is made by part numbers. When LIN is available, FS1B ther LIN, nor FS1B functions are used, this pin must be left open. |
| 6 | GND_COM | GROUND | Dedicated ground for physical layers |
| 7 | CAN_5V | A_OUT | Output voltage for the embedded CAN FD interface |
| 8 | CANH | A_IN/OUT | CAN output high. If CAN function is not used, this pin must be left open. |
| 9 | CANL | A_IN/OUT | CAN output low. If CAN function is not used, this pin must be left open. |

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Table 3. FS6500/FS4500 pin definition...continued

| 12 IO_6 13 FCF 14 FS0 15 DEE 16 AGI | _5/VKAM | D_IN A_OUT A_IN D_IN A_OUT A_IN D_IN | Can be used as digital input (load dump proof) with wake-up capability or as an output gate driver Digital input: Pin status can be read through the SPI. Can be used to monitor error signals from another IC for safety purposes (when used with IO_5). Wake-up capability: Can be selectable to wake-up on edges or levels. Output gate driver: Can drive a logic level low-side NMOS transistor. Controlled by the SPI. Can be used as digital input with wake-up capability or as an analog output providing keep alive memory supply in low-power mode. Analog input: Pin status can be read through the MUX output terminal Digital input: Pin status can be read through the SPI. Can be used to monitor error signals from another IC for safety purposes (when used with IO_4). Wake-up capability: Can be selectable to wake-up on edges or levels. Supply output: Provide keep alive memory supply in low-power mode Can be used as analog or digital input (load dump proof) with wake-up capability (selectable) Analog input: Pin status can be read through the MUX output terminal Digital input: Pin status can be read through the SPI. Wake-up capability: Can be selectable to wake-up on edges or levels. Feedback core resistor bridge monitoring: For safety purposes, this pin is used to monitor the middle point of a redundant resistor bridge connected on V _{CORE} (in parallel to the one used to set the V _{CORE} voltage). If not used, this pin must be |
|--|---------------|--|--|
| 12 IO_6 13 FCF 14 FS0 15 DEE 16 AGI 17 MU 18 IO_ | _0 | D_IN A_OUT A_IN D_IN | providing keep alive memory supply in low-power mode. Analog input: Pin status can be read through the MUX output terminal Digital input: Pin status can be read through the SPI. Can be used to monitor error signals from another IC for safety purposes (when used with IO_4). Wake-up capability: Can be selectable to wake-up on edges or levels. Supply output: Provide keep alive memory supply in low-power mode Can be used as analog or digital input (load dump proof) with wake-up capability (selectable) Analog input: Pin status can be read through the MUX output terminal Digital input: Pin status can be read through the SPI. Wake-up capability: Can be selectable to wake-up on edges or levels. Feedback core resistor bridge monitoring: For safety purposes, this pin is used to monitor the middle point of a redundant resistor bridge connected on V _{CORE} (in |
| 13 FCF 14 FS0 15 DEE 16 AGI 17 MU 18 IO_ | | D_IN | (selectable) Analog input: Pin status can be read through the MUX output terminal Digital input: Pin status can be read through the SPI. Wake-up capability: Can be selectable to wake-up on edges or levels. Feedback core resistor bridge monitoring: For safety purposes, this pin is used to monitor the middle point of a redundant resistor bridge connected on V _{CORE} (in |
| 14 FS0 15 DEE 16 AGI 17 MU 18 IO_ | RBM | A_IN | monitor the middle point of a redundant resistor bridge connected on V _{CORE} (in |
| 15 DEE 16 AGI 17 MU 18 IO_ | | | connected directly to FB_CORE. |
| 16 AGI 17 MUZ 18 IO_ | 0B | D_OUT | First output of the safety block (active low). The pin is asserted low at start-up and when a fault condition is detected. Open drain structure. |
| 17 MU2 18 IO_2 | BUG | D_IN | Debug mode entry input |
| 18 IO_: | SND | GROUND | Analog ground connection |
| | JX_OUT | A_OUT | Multiplexed output to be connected to a MCU ADC. Selection of the analog parameter is available at MUX-OUT through the SPI. |
| | _2:3 | D_IN | Digital input pin with wake-up capability (logic level compatible) Digital input: Pin status can be read through the SPI. Wake-up capability: Can be selectable to wake-up on edges or levels. |
| 20 TXE | D | D_IN | Transceiver input from the MCU which controls the state of the CAN-bus. Internal pull-up to VDDIO. If CAN function is not used, this pin must be left open. |
| 21 RXI | D | D_OUT | Receiver output which reports the state of the CAN-bus to the MCU If CAN function is not used, this pin must be left open. |
| 22 TXE | DL | D_IN | Transceiver input from the MCU controlling the state of the LIN bus. Internal pull-up to VDDIO. |
| or V | VPU_FS | A_OUT | Pull-up output for FS1B function. |
| is no | not, and vice | e versa. | exclusive. The differentiation is made by part numbers. When LIN is available, FS1B ctions are used, this pin must be left open. |
| 23 RXI | | D_OUT | Receiver output reporting the state of the LIN bus to the MCU. If LIN function is not used, this pin must be left open. |

Table 3. FS6500/FS4500 pin definition...continued

| Pin number | Pin name | Туре | Definition |
|---------------|---------------|----------|--|
| 24 | RSTB | D_OUT | This output is asserted low when the safety block reports a failure. The main function is to reset the MCU. Reset input voltage is also monitored in order to detect external reset and fault condition. Open drain structure. |
| 25 | MISO | D_OUT | SPI bus. Master input slave output |
| 26 | MOSI | D_IN | SPI bus. Master output slave input |
| 27 | SCLK | D_IN | SPI Bus. Serial clock |
| 28 | NCS | D_IN | Not chip select (active low) |
| 29 | INTB | D_OUT | This output pin generates a low pulse when an Interrupt condition occurs. Pulse duration is configurable. Internal pull-up to VDDIO. |
| 30 | VDDIO | A_IN | Input voltage for MISO output buffer. Allows voltage compatibility with MCU I/Os. |
| 31 | SELECT | D_IN | Hardware selection pin for VAUX and VCCA output voltages |
| 32 | FB_CORE | A_IN | VCORE voltage feedback. Input of the error amplifier. |
| 33 | COMP_ CORE | A_OUT | Compensation network. Output of the error amplifier. For FS4500 series, this pin must be left open (NC). |
| 34 | VCORE_ SNS | A_IN | VCORE input voltage sense |
| 35 | SW_CORE | A_OUT | VCORE output switching point for FS6500 series |
| | or VCORE | A_OUT | VCORE output voltage for FS4500 series |
| 36 | BOOT_ CORE | A_IN/OUT | Bootstrap capacitor for VCORE internal NMOS gate drive For FS4500 series, this pin must be left open (NC). |
| 37 | VPRE | A_IN | VPRE input voltage sense |
| 38 | VAUX | A_OUT | VAUX output voltage. External PNP ballast transistor. Collector connection |
| 39 | VAUX_B | A_OUT | VAUX voltage regulator. External PNP ballast transistor. Base connection |
| 40 | VAUX_E | A_OUT | VAUX voltage regulator. External PNP ballast transistor. Emitter connection |
| 41 | VCCA_E | A_OUT | VCCA voltage regulator. External PNP ballast transistor. Emitter connection |
| 42 | VCCA_B | A_OUT | VCCA voltage regulator. External PNP ballast transistor. Base connection |
| 43 | VCCA | A_OUT | VCCA output voltage. External PNP ballast transistor. Collector connection |
| 44 | GATE_LS | A_OUT | Low-side MOSFET gate drive for non-inverting buck-boost configuration |
| 45 | DGND | GROUND | Digital ground connection |
| 46 | BOOT_PRE | A_IN/OUT | Bootstrap capacitor for the VPRE internal NMOS gate drive |
| 47 | SW_PRE2 | A_OUT | Second pre-regulator output switching point |
| 48 | SW_PRE1 | A_OUT | First pre-regulator output switching point |

8 Maximum ratings

Table 4. Maximum ratings

All voltages are with respect to ground, unless otherwise specified. Exceeding these ratings may cause a malfunction or permanent damage to the device.

| Symbol | Ratings | Value | Unit | Notes |
|-------------------------|---|-------------|------|-------|
| Electrical ratio | ngs | | | |
| V _{SUP1/2/3} | DC voltage at power supply pins | -1.0 to 40 | V | [1] |
| V _{SENSE} | DC voltage at battery sense pin (with ext R in series mandatory) | -14 to 40 | V | |
| V _{SW1,2} | DC voltage at SW_PRE1 and SW_PRE2 Pins | -1.0 to 40 | V | |
| V _{PRE} | DC voltage at VPRE Pin | -0.3 to 8 | V | |
| V _{GATE_LS} | DC voltage at Gate_LS pin | -0.3 to 8 | V | |
| V _{BOOT_PRE} | DC voltage at BOOT_PRE pin | -1.0 to 50 | V | |
| V _{SW_CORE} | DC voltage at SW_CORE pin | -1.0 to 8 | V | |
| V _{CORE_SNS} | DC voltage at VCORE_SNS pin | 0.0 to 8 | V | |
| V _{BOOT_CORE} | DC voltage at BOOT_CORE pin | 0.0 to 15 | V | |
| V _{FB_CORE} | DC voltage at FB_CORE pin | -0.3 to 2.5 | V | |
| V _{COMP_CORE} | DC voltage at COMP_CORE pin | -0.3 to 2.5 | V | |
| V _{FCRBM} | DC voltage at FCRBM pin | -0.3 to 8 | V | |
| V _{AUX_B,E} | DC voltage at VAUX_B, VAUX_E pins | -0.3 to 40 | V | |
| V _{AUX} | DC voltage at VAUX pin | -2.0 to 40 | V | |
| V _{CCA_B,E} | DC voltage at VCCA_B, VCCA_E pins | -0.3 to 8 | V | |
| V _{CCA} | DC voltage at VCCA pin | -0.3 to 8 | V | |
| V_{DDIO} | DC voltage at VDDIO pin | -0.3 to 8 | V | |
| V _{CAN_5V} | DC voltage on CAN_5V pin | -0.3 to 8 | V | |
| V _{PU_FS} | DC voltage at VPU_FS pin | -0.3 to 8 | V | |
| V _{FSxB} | DC voltage at FS0B, FS1B pins (with ext R in series mandatory) | -0.3 to 40 | V | |
| V _{DEBUG} | DC voltage at DEBUG pin | -0.3 to 40 | V | |
| V _{IO_0,4} | DC voltage at IO_0, IO_4 pins (with ext R in series mandatory) | -0.3 to 40 | V | |
| V _{IO_5} | DC voltage at IO_5 pin | -0.3 to 20 | V | |
| V _{KAM} | DC voltage at VKAM pin | -0.3 to 8 | V | |
| V_{DIG} | DC voltage at INTB, RSTB, MISO, MOSI, NCS, SCLK, MUX_OUT, RXD, TXD, TXDL, IO_2, IO_3 pins | -0.3 to 8 | V | |
| V _{SELECT} | DC voltage at SELECT pin | -0.3 to 8 | V | |
| V _{BUS_CAN} | DC voltage on CANL, CANH pins | –27 to 40 | V | |
| I_lsense | V _{SENSE} maximum current capability | -5.0 to 5.0 | mA | |
| I_IO _{0, 4, 5} | IOs maximum current capability (IO_0, IO_4, IO_5) | -5.0 to 5.0 | mA | |
| ESD voltage | | | | |
| Human body | model (JESD22/A114) ⁽¹⁹⁾ – 100 pF, 1.5 kΩ | | | |
| V _{ESD-HBM1} | • All pins | ±2.0 | kV | [2] |
| V _{ESD-HBM2} | VSUP1, 2, 3, VSENSE, VAUX, IO_0,4, FS0B, FS1B, DEBUG | ±4.0 | kV | |
| V _{ESD-HBM3} | CANH, CANL | ±6.0 | kV | |
| V _{ESD-HBM4} | • LIN | ±8.0 | kV | |

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Table 4. Maximum ratings ...continued

All voltages are with respect to ground, unless otherwise specified. Exceeding these ratings may cause a malfunction or permanent damage to the device.

| Symbol | Ratings | Value | Unit | Notes |
|------------------------|--|------------|------|-------|
| Charge devic | e model (JESD22/C101) ⁽²⁰⁾ : | | | |
| V _{ESD-CDM1} | All pins | ±500 | V | |
| V _{ESD-CDM2} | Corner pins | ±750 | V | |
| System level | ESD (gun test) | | | |
| | VSUP1, 2, 3, VSENSE, VAUX, IO_0, 4, 5, FS0B, FS1B | | | |
| V _{ESD-GUN1} | 330 Ω/150 pF unpowered according to IEC 61000-4-2: ⁽¹⁶⁾ | ±8.0 | kV | |
| V _{ESD-GUN2} | 330 Ω/150 pF unpowered according to OEM LIN, CAN, FlexRay Conformance | ±8.0 | kV | |
| V _{ESD-GUN3} | $2.0 \text{ k}\Omega/150 \text{ pF}$ unpowered according to ISO $10605^{(15)}$ | ±8.0 | kV | |
| V _{ESD-GUN4} | $2.0~\text{k}\Omega/330~\text{pF}$ powered according to ISO $10605^{(15)}$ | ±8.0 | kV | |
| | CANH, CANL | | | |
| V _{ESD-GUN5} | 330 Ω/150 pF unpowered according to IEC 61000-4-2: ⁽¹⁶⁾ | ±15.0 | kV | |
| V _{ESD-GUN6} | 330 Ω/150 pF unpowered according to OEM LIN, CAN, FlexRay Conformance | ±12.0 | kV | |
| V _{ESD-GUN7} | 2.0 kΩ/150 pF unpowered according to ISO 10605 $^{(15)}$ | ±15.0 | kV | |
| V _{ESD-GUN8} | $2.0~k\Omega/330~pF$ powered according to ISO $10605^{(15)}$ | ±12.0 | kV | |
| | • LIN | | | |
| V _{ESD-GUN9} | 330 Ω/150 pF unpowered according to IEC 61000-4-2: ⁽¹⁶⁾ | ±12.0 | kV | |
| V _{ESD-GUN10} | 330 Ω/150 pF unpowered according to OEM LIN, CAN, FlexRay conformance | ±12.0 | kV | |
| V _{ESD-GUN11} | $2.0 \text{ k}\Omega/150 \text{ pF}$ unpowered according to ISO $10605^{(15)}$ | ±12.0 | kV | |
| V _{ESD-GUN12} | $2.0~\text{k}\Omega/330~\text{pF}$ powered according to ISO $10605^{(15)}$ | ±12.0 | kV | |
| Thermal ratin | gs | | | |
| T _A | Ambient temperature | -40 to 125 | °C | |
| TJ | Junction temperature | -40 to 150 | °C | |
| T _{STG} | Storage temperature | -55 to 150 | °C | |
| Thermal resis | stance | | | |
| $R_{\theta JA}$ | Thermal resistance junction to ambient | 30 | °C/W | [3] |
| R ₀ JCTOP | Thermal resistance junction to case top | 23.8 | °C/W | [4] |
| $R_{\theta JCBOTTOM}$ | Thermal resistance junction to case bottom | 0.9 | °C/W | [5] |

All V_{SUPS} ($V_{SUP1/2/3}$) must be connected to the same supply (Figure 1). Compared to AGND.

^[1] [2]

Per JEDEC JESD51-6⁽¹⁷⁾ with the board (JESD51-7)⁽¹⁸⁾ horizontal. [3]

^[4] Thermal resistance between the die and the case top surface as measured by the cold plate method (MIL SPEC - 883 Method 1012.1)(21)

Thermal resistance between the die and the solder pad on the bottom of the packaged based on simulation without any interface resistance.

9 Packaging

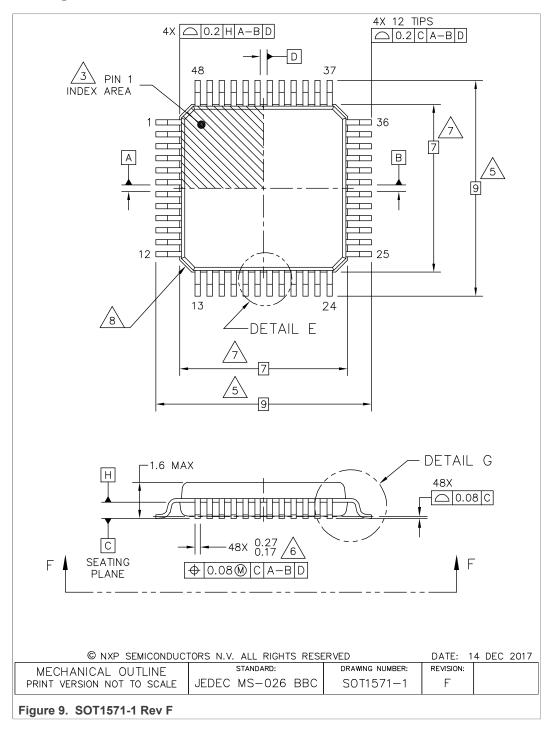
9.1 Package mechanical dimensions

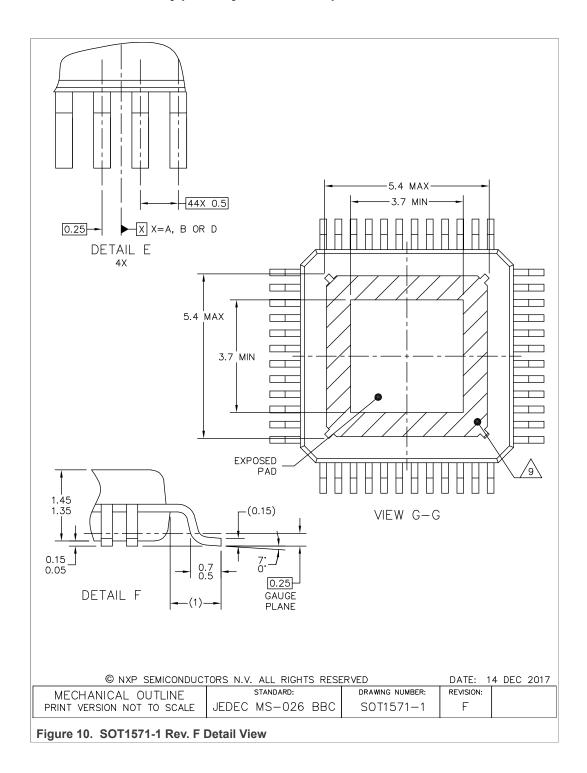
Package dimensions are provided in package drawings. To find the most current package outline drawing, go to www.nxp.com and perform a keyword search for the drawing's document number.

Table 5. Package mechanical dimensions

| Package | Suffix | Package outline drawing number |
|--|--------|--------------------------------|
| 7.0×7.0 , 48–Pin LQFP exposed pad, with 0.5 mm pitch, and a 4.5 × 4.5 exposed pad | AE | 98ASA00173D |

9.2 Package outline





NOTES: 1. DIMENSIONS ARE IN MILLIMETERS. 2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M-1994. $\sqrt{3}$. PIN 1 FEATURE SHAPE, SIZE AND LOCATION MAY VARY. 4. DATUMS A, B AND D TO BE DETERMINED AT DATUM PLANE H. $\sqrt{5}$ dimension to be determined at seating plane c. $\stackrel{\frown}{6}$ this dimension does not include dambar protrusion. Allowable dambar PROTRUSION SHALL NOT CAUSE THE LEAD WIDTH TO EXCEED THE UPPER LIMIT BY MORE THAN 0.08MM AT MAXIMUM MATERIAL CONDITION. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSION AND ADJACENT LEAD SHALL NOT BE LESS THAN 0.07MM. THIS DIMENSION DOES NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.25MM PER SIDE. THIS DIMENSION IS MAXIMUM PLASTIC BODY SIZE DIMENSION INCLUDING MOLD MISMATCH. /8\ EXACT SHAPE OF EACH CORNER IS OPTIONAL. $\cancel{9}$ hatched area to be keep out zone for PCB routing. © NXP SEMICONDUCTORS N.V. ALL RIGHTS RESERVED DATE: 14 DEC 2017 STANDARD: DRAWING NUMBER: REVISION: MECHANICAL OUTLINE

JEDEC MS-026 BBC

SOT1571-1

F

PRINT VERSION NOT TO SCALE

Figure 11. SOT1571-1 Rev F Notes

10 Soldering

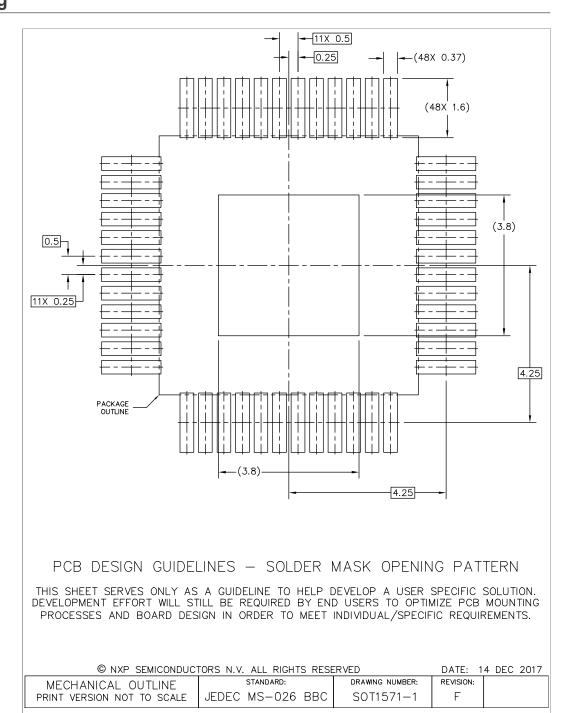
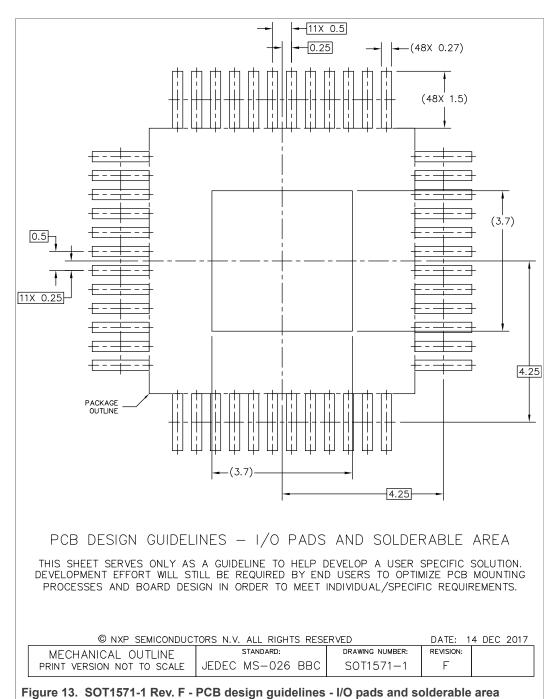
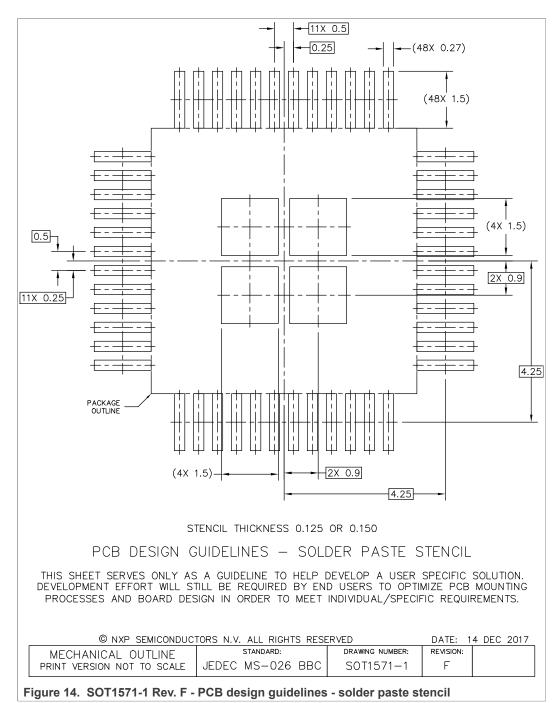


Figure 12. SOT1571-1 Rev. F - PCB design guidelines - solder mask opening pattern





11 References

Obtain additional information on related NXP products and application solutions through the documents and URLs listed below.

- (1) **AN5238** FS6500 and FS4500 Safe System Basis Chip Hardware Design and Product Guidelines Application Note https://www.nxp.com/AN5238-DOWNLOAD
- (2) AN4388 Quad Flat Package (QFP) https://www.nxp.com/files/analog/doc/app_note/AN4388.pdf
- (3) **FS6500-FS4500PDTCALC** Power dissipation tool (Excel File) https://www.nxp.com/files/analog/software_tools/FS6500-FS4500-power-dissipation-calculator.xlsx
- (4) V_{CORE} compensation network simulation tool (CNC)^[1]
- (5) **FMEDA** FS6500/FS4500 ASILB FMEDA^[1]
- (6) UM11498 FS6500/FS4500 ASILB Safety manual user guide
- (7) KITFS6507LAEEVM FS6507, System Basis Chip, ASIL B, DC-DC 0.8 A Vcore, LDT, CAN, LIN https://www.nxp.com/KITFS6507LAEEVM
- (8) KITFS4508CAEEVM FS4508, System Basis Chip, ASIL B, Linear 0.5 A Vcore, FS1b, LDT, CAN https://www.nxp.com/KITFS4508CAEEVM
- (9) FS6500 product summary page https://www.nxp.com/FS6500
- (10) FS4500 product summary page https://www.nxp.com/FS4500
- (11) Analog power management homepage https://www.nxp.com/products/power-management
- (12) **ISO 11898-2:2003** Road vehicles Controller area network (CAN) Part 2: High-speed medium access unit https://www.iso.org/standard/33423.html
- (13) **ISO 11898-5:2007** Road vehicles Controller area network (CAN) Part 5: High-speed medium access unit with low-power mode https://www.iso.org/contents/data/standard/04/12/41284.html
- (14) ISO 7637-2:2011 Road vehicles Electrical disturbances from conduction and coupling Part 2: Electrical transient conduction along supply lines only https://www.iso.org/standard/50925.html
- (15) ISO 10605:2008 Road vehicles Test methods for electrical disturbances from electrostatic discharge https://www.iso.org/standard/41937.html
- (16) IEC 61000-4-2:2008 Electromagnetic compatibility (EMC) Part 4-2: Testing and measurement techniques -Electrostatic discharge immunity test https://webstore.iec.ch/publication/4189
- (17) **JESD51-6** INTEGRATED CIRCUIT THERMAL TEST METHOD ENVIRONMENTAL CONDITIONS FORCED CONVECTION (MOVING AIR)
- (18) **JESD51-7** HIGH EFFECTIVE THERMAL CONDUCTIVITY TEST BOARD FOR LEADED SURFACE MOUNT PACKAGES
- (19) JESD22-A114F ELECTROSTATIC DISCHARGE (ESD) SENSITIVITY TESTING HUMAN BODY MODEL (HBM)
- (20) **JESD22-C101F** FIELD-INDUCED CHARGED-DEVICE MODEL TEST METHOD FOR ELECTROSTATIC DISCHARGE WITHSTAND THRESHOLDS OF MICROELECTRONIC COMPONENTS
- (21) MIL-STD-883-1, Method 1012.1 TEST METHOD STANDARD MICROCIRCUITS

FS6500-FS4500SDS-ASILB

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- (22) LIN Specification Package Revision 2.1:2006
 https://www.lin-cia.org/fileadmin/microsites/lin-cia.org/resources/documents/LIN-Spec_Pac2_1.pdf
- (23) LIN Specification Package Revision 2.2A:2010 https://www.lin-cia.org/fileadmin/microsites/lin-cia.org/resources/documents/LIN_2.2A.pdf
- (24) SAE J2602-2:201211 LIN Network for Vehicle Applications Conformance Test https://www.sae.org/standards/content/j2602/2_201211/
- [1] Available upon request.

12 Revision history

Table 6. Revision history

| Document ID | Release date | Data sheet status | Supersedes | | | |
|------------------------------|---|-------------------|------------------------------|--|--|--|
| FS6500-FS4500SDS-ASILB v.3.0 | 20210414 | Product | FS6500-FS4500SDS-ASILB v.2.0 | | | |
| Modifications | Section 1: replaced "0.8 A" by "1.5 A" Section 2: replaced "Family of devices to supply MCU core from 1.0 V to 5.0 V, with SMPS (0.8 A) or LDO (0.5 A)" to "Family of devices to supply MCU core from 1.0 V to 5.0 V, with SMPS (0.8 A, 1.5 A or 2.2 A) or LDO (0.5 A)" Section 5: updated Table 1 and Table 2 (added new part numbers) | | | | | |
| FS6500-FS4500SDS-ASILB v.2.0 | 20210111 | Product | FS6500-FS4500SDS-ASILB v.1.3 | | | |
| Modifications | Revised data sheet status from "Preliminary" to "Product". Section 5.2, revised Table 2 changing "PC33" parts to "MC33" Section 7.2, pin number 11, removed "VKAM can be enabled or disabled by default at power up. The differentiation is made by part numbers." | | | | | |
| FS6500-FS4500SDS-ASILB v.1.3 | 20201106 | Preliminary | _ | | | |
| Modifications | Initial release (Short data sheet version aligned to full data sheet, FS6500, FS4500: ASILB, v.1.3) | | | | | |

13 Legal information

13.1 Data sheet status

| Document status ^{[1][2]} | Product status ^[3] | Definition |
|-----------------------------------|-------------------------------|---|
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FS6500-FS4500SDS-ASILB

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Safety power system basis chip with CAN FD and LIN transceivers

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