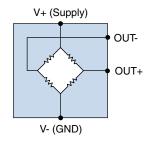
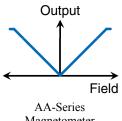


AA/AB-Series Analog Magnetic Sensors

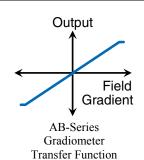
Equivalent Circuit



Idealized Transfer Functions







<u>Features</u>

- Magnetometer and gradiometer configurations
- Field ranges from <<1 Oe to >4000 Oe
- Ultrasensitive, high-field, and low-hysteresis versions
- Wheatstone bridge analog outputs
- Operation to near-zero voltage
- Up to 1 MHz
- Up to 150°C operating temperature
- ULLGA4, TDFN6, MSOP8, and SOIC8 packages

Applications

- Motion, speed, and position control
- Low-field sensing
- Motor commutator sensors
- Noncontact current sensing

Description

NVE's analog GMR sensors have high sensitivity, excellent temperature stability, and small size. Their versatility and wide sensing range makes them an excellent choice for a variety of analog sensing applications including industrial and automotive position, speed, and current sensors.

The sensors are configured as inherently temperaturecompensating Wheatstone bridges.

AA-Series sensors are magnetometers, which detect absolute magnetic field. AB-Series sensors are differential gradiometers, which detect field gradients.

Three magnetometer subtypes are available: the standard AA-Series; the ultrasensitive "H" subtype; the high-field, kilooersted range "K" subtype, and the low-hysteresis "L" subtype.

Packages are as small as an ultraminiature 1.1 x 1.1 mm ULLGA4.





Absolute Maximum Ratings

Parameter		Symbol	Min.	Max.	Units
	AAxxx/ABxxx/AAL002			24	
Supply voltage	AAHxxx/AAKxxx/ABHxxx/ AAL004/AAL024	V_{cc}		12	Volts
On arating tamparatura	AAxxx/AAKxxx/ABxxx/AALxxx		-50	125	°C
Operating temperature	AAHxxx/ABHxxx		-30	150	°C
Storago tomporaturo	AAxxx/AAKxx/ABxxx/AALxxx		-65	135	°C
Storage temperature	AAHxxx/ABHxxx		-65	150	C
ESD (Human Body Mode	el)			400	Volts
Applied magnetic field	Н		Unlimited	Oe	
Voltage from sensor conn (applies to TDFN packa			63	Volts DC	





Operating Specifications

Parameter		Symbol	Min.	Тур.	Max.	Units	Test Condition	
	AAHxxx/AAKxxx/	•			12		Maximum	
Supply voltage	ABHxxx/AAL004	V_{cc}	<1		12	Volts	limited by power	
11 7 8	AAxxx/ABxxx/AAL002	CC			24		dissipation	
0	AAKxxx	т.	-40		85			
Operating	AAxxx/ABxxx/AALxxx	$T_{\text{min}};$ T_{max}	-50		125	°C		
temperature	AAHxxx/ABHxxx	1 _{MAX}	-30		150			
Electrical	AAxxx/AAKxxx/AALxxx/ABxxx	V_{O}	-4		+4	mV/V		
offset	AAHxxx/ABHxxx	• 0	-5		+5	111 V / V		
Output at	AAxxx/ABxxx			60				
maximum	AAHxxx/ABHxxx	$ m V_{OUT ext{-}MAX}$		40		mV/V		
field	AAKxxx	* OUI-MAX	19	25		111 1 / 1		
	AALxxx			45				
Nonlinearity	AAxxx/AAKxxx/ABxxx/AAL002			4	2	%		
	AAH			4			Unipolar field	
Hantanasia	AAHxxx/ABHxxx			15	4	%	sweep	
Hysteresis	AAxxx/AAKxxx/ABxxx AALxxx				2	, ,		
Resistance tolera			-20		+20	%	25°C	
Resistance tolera	AAxxx/ABxxx		20	+0.14	120	/0	23 C	
Resistance vs.	AAHxxx/AAKxxx/	TC_R				%/°C	No applied field	
temperature	AALxxx/ABHxxx	1 C _K		+0.11		, ,,	The state of the s	
	AAxxx/ABxxx			+0.03		%/°C	Constant-current	
	AAHxxx/ABHxxx	TO		+0.1				
	AAKxxx	TC_{O-I}		+0.13			supply	
Output	AALxxx			-0.28			-1.	
temperature	AAxxx/ABxxx			-0.1				
coefficient	AAHxxx/ABHxxx	TC _{O-V}		0		%/°C	Constant-voltage	
	AAKxxx	1C _{0-V}		-0.3		70/ C	supply	
	AALxxx			-0.4				
	AAKxxx	TC_{HSAT}		-0.19		%/°C		
Operating	AAKxxx				50	kHz		
frequency	AAxxx/AAHxxx/AALxxx	f_{MAX}	DC		100	kHz		
	ABxxx/ABHxxx				1	MHz		
Junction-	ULLGA4 (-14 suffix)			500				
Ambient	TDFN6 (-10 suffix)	0		320		°C/W		
thermal	MSOP8 (-00 suffix)	$ heta_{\scriptscriptstyle \mathrm{JA}}$		320		°C/W		
resistance	SOIC8 (-02 suffix)			240			Soldered to	
	ULLGA4 (-14 suffix)			100			double-sided board; free air	
Power	TDFN6 (-10 suffix)	D		500		***	Joana, free an	
Dissipation	MSOP8 (-00 suffix)	P_{D}		500		mW		
•	SOIC8 (-02 suffix)	1		675	1			



Operation

Sensor Subtypes

There are four AA/AB-Series subtypes, as summarized in the table below. "H" subtypes are designed for very high sensitivity, and "K" types have low sensitivity and high saturation for high-field sensing. "L" types offer low hysteresis. AAH-Series parts also have a 150°C maximum temperature specification.

Parameter	AAxxx/ ABxxx	AAHxxx/ ABHxxx	AAKxxx	AALxxx
Field Sensitivity	High	Very High	Low	High
Operating Field Range	High	Low	Very High	Medium
Hysteresis	Medium	High	Medium	Low
Max. Temperature	High	Very High	Commercial	High

Magnetometer Operation

AA-Series sensors are *magnetometers*, which detect the absolute magnetic field.

Direction of Sensitivity

Unlike Hall effect or other sensors, the direction of sensitivity of GMR sensors is in the plane of the package, which more convenient for many applications. Two permanent magnet orientations that will activate the sensor are shown in Figure 1:

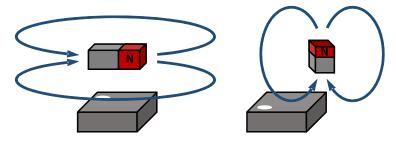


Figure 1. Planar magnetic sensitivity.

Omnipolar

AA-Series sensors are "omnipolar," meaning the output is equally sensitive to either magnetic field polarity and the output is always a positive voltage:

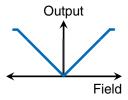


Figure 2. The omnipolar response of AA-Series sensors.

Standard and Cross-Axis Axis Directional Sensitivity

The standard axis of sensitivity is along the part axis, but there are some parts available with cross-axis sensitivity, and AAKxxx sensors are not directionally sensitive in the IC plane, and are therefore sensitive in both standard and cross-axis axis directions.



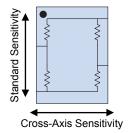


Figure 3. Standard versus cross-axis-sensitivity for AA-Series sensors.

Gradiometer Operation

AB-Series sensors are differential *gradiometers* that reject common mode magnetic fields, making them ideal for high magnetic noise environments such as near electric motors or current-carrying wires. The devices are sensitive to a field gradient along the part axis.

The figure below shows a typical gradiometer response:

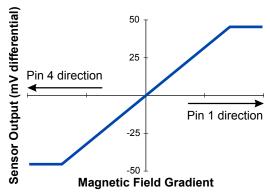


Figure 4. Typical AB-Series gradiometer response.



Typical Performance Graphs

Figures 5–7 show the response of three types of high-sensitivity models. The standard version, the AA002, has excellent temperature stability, especially with constant-current drive. The **AAH002** has very high sensitivity but more temperature dependence, and the **AAL**002 offers low hysteresis at the expense of more temperature dependence:

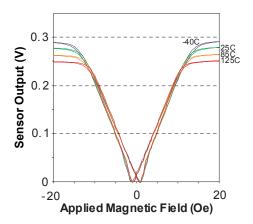


Figure 5a. Typical AA002 output with 1 mA constant-current drive.

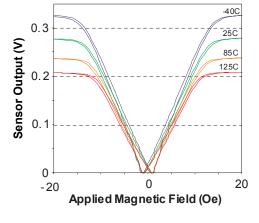


Figure 5b. Typical AA002 output with a 5V supply.

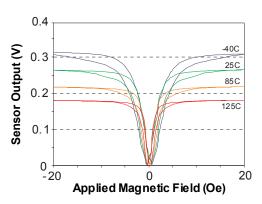


Figure 6a. Typical AAH002 output with 2.28 mA constant-current drive.

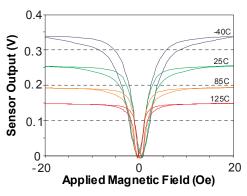


Figure 6b. Typical AAH002 output with a 5V supply.

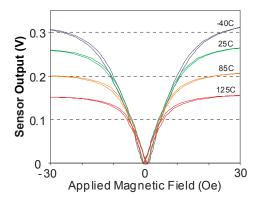


Figure 7a. Typical AAL002 output with 1 mA constant-current drive.

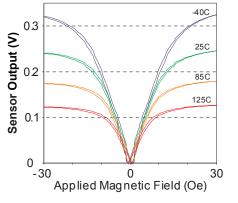


Figure 7b. Typical AAL002 output with a 5V supply.





Figure 8 shows the typical ouput of an AAK001 high-field sensor. The sensor responds from zero field to 4 kOe, and is are highly linear from 400 Oe to 2.5 kOe. The saturation field is dependant on temperature, but sensitivity is quite stable with temperature.

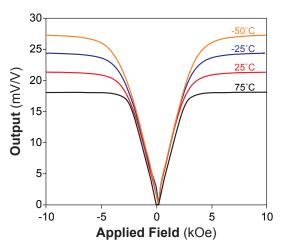


Figure 8. AAK001 high-field sensor output.



Illustrative Applications

Traditional Differential Amplifier

Traditional differential amplifiers use low-cost op-amps to provide a single-ended analog output. The circuit below has a gain of 20, which provides a full-scale output at slightly less than the sensor's saturation. A low-cost, low bias current op amp allows large resistors to avoid loading the sensor bridge. The 250 K Ω input resistors are 100 times the 2.5 K Ω sensor output impedance to avoid loading.

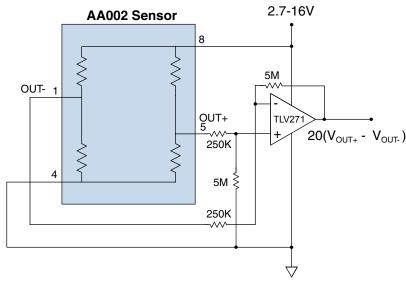


Figure 9. Traditional op-amp differential amplifier.

Sensor Instrumentation Amplifier

Instrumentation amplifiers such as the INA826 are popular bridge sensor preamplifiers because they have a low component count and have excellent common-mode rejection ratios without needing to match resistors. These amplifiers can run on single or dual supplies. AC coupling can be used for small, dynamic signals.

The circuit below has a gain of 20. The general equation for the output voltage is:

$$V_{OUT} = (1 + 49.4 \text{K} / R_G)V_{IN} + V_{REF}; V_{IN} = V_{OUT} - V_{OUT}$$

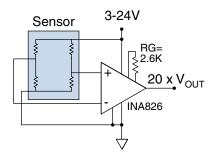


Figure 10. Single-ended analog sensor instrumentation amplifier.

Note that the instrumentation amplifier has a minimum output of 0.1V, so to detect very low fields on a single supply, an offset can be provided by using a non-zero V_{REF} .



Constant-Current Sensor Drive

Using a constant current rather than conventional constant voltage sensor supply can significantly improve temperature stability of AAxxx/ABxxx sensors. AA00x sensors, for example, have an output temperature coefficient (TC_{O-I}) of 0.03%/°C with constant current, versus -0.1%/°C with constant voltage (TC_{O-V}).

A simple constant-current supply is illustrated below:

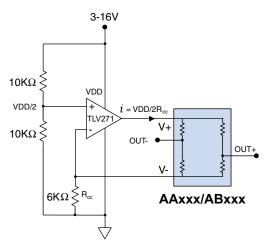


Figure 11. Constant-current supply.

The supply current for the circuit above is $V_{cc}/2R_{cc}$. R_{cc} can be set to the maximum sensor bridge resistance (e.g., 6 K Ω for many sensors) to provide the highest possible output without saturating the op-amp. The sensor will be driven with 1 mA for a 12 V supply in the circuit above. Similar op-amp or instrumentation amplifiers can be used for constant-current or constant-voltage supplies.

Variable Threshold Magnetic Switch

NVE offers AD-Series factory-set GMR Switches, but AA-Series analog sensors can be used for special thresholds or hysteresis, or for variable thresholds. In this circuit, the threshold is varied by changing R_G , which sets the gain of the differential amplifier. The 1 M Ω resistor sets the threshold hysteresis:

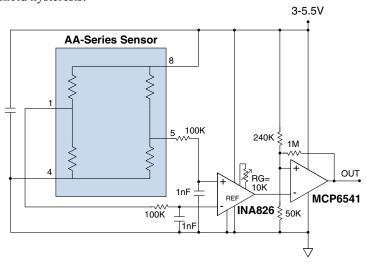


Figure 12. Variable threshold magnetic switch.



LED Field-Strength Indicator

The op-amp circuit in Figure 13 below can be used to change the brightness of an LED to indicate magnetic field strength at a glance:

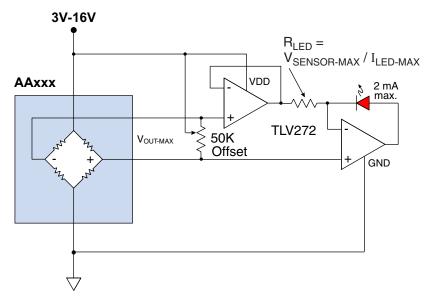


Figure 13. LED brightness indicates the magnetic field.

The LED current is proportional to the sensor output:

$$I_{LED} = (V_{OUT^+} - V_{OUT^-}) / R_{LED}$$

The maximum LED current can be set to the maximum sensor output. For example, for an AAK001, typical $V_{\text{OUT-MAX}}$ is 25 mV/V, so for a three-volt supply the maximum is approximately 75 mV. For a high-efficiency with a forward current of 2 mA, $R_{\text{LED}} = 75 \text{ mV} / 2 \text{ mA} = \underline{38\Omega}$.

The 50 K Ω potentiometer is optional, to correct for sensor offset or to set the minimum field to turn on the LED.

The 16-volt maximum supply voltage noted in Figure 13 is limited by the op-amp selected, but note that some sensors have a 12-volt maximum supply rating. The three-volt minimum supply is to provide enough voltage to turn on the LED; the sensors can operate on lower voltages.

Noncontact Current Sensing

AA-Series sensors are often used to measure the current over a circuit board trace. The sensor measures the current by detecting the magnetic field generated by the current through the trace.

The AAL024 is ideal for this application because its cross-axis sensitivity provides sensitivity to a current trace directly under the part, and its low hysteresis provides repeatability. The AA003-02 is popular for overcurrent protection where hysteresis is needed and high accuracy is not required.

Typical current sensing configurations are shown below:



Figure 14a. 0.09" (2.3 mm) trace (0 – 10 A with an AA003 sensor)



Figure 14b. 0.05" (1.3 mm) trace (0-5) A with an AAL024 sensor).



Figure 14c. Five turns of 0.0055" (0.14 mm) trace (0 – 1 A with an AAL024 sensor).



For the geometry shown in Figure 15 and narrow traces, the magnetic field generate can be approximated by Ampere's law:

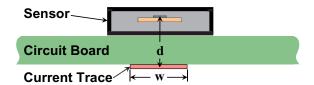


Figure 15. The geometry of current-sensing over a circuit board trace.

$$H = \frac{2I}{d}$$
 ["H" in oersteds, "I" in amps, and "d" in millimeters]

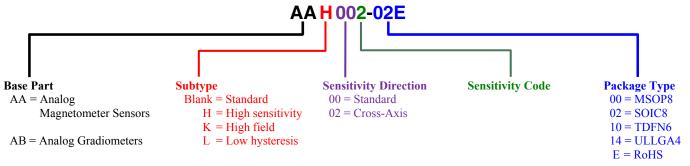
The trace can also be run on the top side of the PCB for more current sensitivity.

More precise calculations can be made by breaking the trace into a finite element array of thin traces, and calculating the field from each array element. We have a free, Web-based application with a finite-element model to estimate magnetic fields and sensor outputs in this application:

www.nve.com/spec/calculators.php#tabs-Current-Sensing



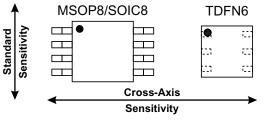
Part Numbering



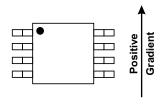
ULLGA4

Direction of Sensitivity

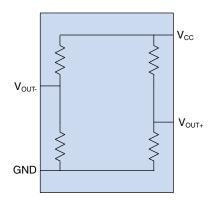
AA-Series (magnetometers)



AB-Series (gradiometers)



Pinouts



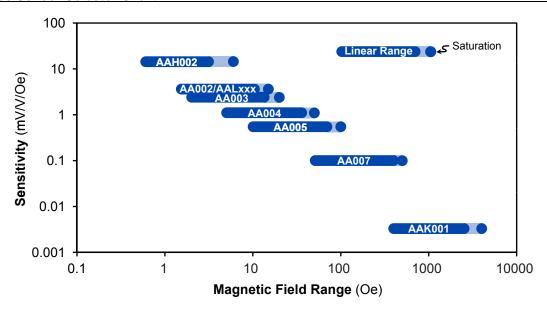
				AA-S	eries Pino	ut
Sensitivity						
	Standard Cross-Ax					
(AA	X00x-x	x)	(AAX	2 x-xx)		
ULLGA	MSOP/ SOIC	TDFN	MSOP/ SOIC	TDFN	Symbol	Description
3	1	1	5	4	V _{OUT} -	Negative bridge output (decreases with increasing field).
	3	2	3	2	NC	No internal connection.
4	4	3	4	3	V-/GND	Negative supply or ground.
1	5	4	1	1	V _{OUT+}	Positive bridge output (increases with field).
	6 7	5	6 7	5	NC	No internal connection.
2	8	6	8	6	V+	Positive supply voltage.
		Center Pad		Center Pad	NC	Internally connected to leadframe

AB-Series Pinout								
Pin	Symbol	Description						
1	V _{OUT} -	Negative bridge output (decreases with gradient).						
2	NC	No internal connection.						
3	110	Tvo internal confection.						
4	V-/GND	Negative supply or ground.						
5	V _{OUT+}	Positive bridge output (increases with gradient).						
6 7	NC	No internal connection.						
8	V+	Positive supply.						

www.nve.com



AA-Series Sensor Selector Chart



Available Parts

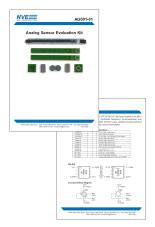
	Magnetometers (AA-Series)										
		Range	Satura-	Sensi (mV/V		Max. Non-	Max. Hyst-	Max.	Тур.		
Available Part	Min.	Max.	tion (Oe)	Min.	Max.	linearity (% Uni.)	eresis (% Uni.)	Operating Temp.	Resist- ance	Package	
AA002-02	1.5	10.5	15	3	4.2	2%	4%	125°C	5 kΩ	SOIC8	
AA003-02	2	14	20	2	3.2	2%	4%	125°C	5 kΩ	SOIC8	
AA004-00	5	35	50	0.9	1.3	2%	4%	125°C	5 kΩ	MSOP8	
AA024-00	5	35	50	0.9	1.3	2%	4%	125°C	5 kΩ	MSOP8 (cross-axis)	
AA004-02	5	35	50	0.9	1.3	2%	4%	125°C	5 kΩ	SOIC8	
AA005-02	10	70	100	0.45	0.65	2%	4%	125°C	5 kΩ	SOIC8	
AA006-00	5	35	50	0.9	1.3	2%	4%	125°C	30 kΩ	MSOP8	
AA006-02	5	35	50	0.9	1.3	2%	4%	125°C	30 kΩ	SOIC8	
AA007-00	50	450	500	0.08	0.12	2%	4%	125°C	5 kΩ	MSOP8	
AAH002-02	0.6	3	6	11	18	4%	15%	150°C	$2 k\Omega$	SOIC8	
AAH004-00	1.5	7.5	15	3.2	4.8	4%	15%	150°C	$2 k\Omega$	MSOP8	
AAL002-02	1.5	10.5	15	3	4.2	2%	2%	125°C	5.5 kΩ	SOIC8	
AAL004-10	1.5	10.5	15	3	4.2	4%	2%	125°C	2.2 kΩ	TDFN6	
AAL024-10	1.5	10.5	15	3	4.2	4%	2%	125°C	2.2 kΩ	TDFN6 (cross-axis)	
AAK001-14	400	2500	4000	0.0025	0.004	2%	4%	85°C	$3.5 \text{ k}\Omega$	ULLGA4	

	Gradiometers (AB-Series)															
		Linear Range (Oe)		Sensitivity (%R/Oe)		•		·		Satura- (%R/C		Max. Non-	Max. Hyst-	Max.	Тур.	
Available			tion			linearity	eresis	Operating	Resist-							
Part	Min.	Max.	(Oe)	Min.	Max.	(% Uni.)	(% Uni.)	Temp.	ance	Package						
AB001-02	10	175	250	0.02	0.03	2%	4%	125°C	2.5 kΩ	SOIC8						
AB001-00	10	175	250	0.02	0.03	2%	4%	125°C	2.5 kΩ	MSOP8						
ABH001-00	5	40	70	0.06	0.12	4%	15%	150°C	1.2 kΩ	MSOP8						



Evaluation Kits

Four inexpensive evaluation kits including AA- or AB-Series analog sensors are available:



AG001-01: Analog Sensor Evaluation Kit

This kit features several types of NVE's AA and AB series parts, a selection of permanent magnets for activation or bias purposes, and circuit boards to mount the parts for testing.



AG003-01: AA003 Current Sensor Evaluation Kit

This kit features a circuit board with different trace configurations running under four AA003-02E analog sensors to evaluate the sensor as non-contact current sensors. The board supports current ranges of 0-9 amps, 0-6 amps, and 0-250 milliamps. Boards measure 2 by 1.85 inches (51 mm by 47 mm), and include four sensors.



AG903-01: AA003 Current Sensor Evaluation Kit

This board includes four ADL024-10E TDFN current sensors on a PCB with four different currenttrace configurations. The boards measure 2 by 2 inches (50 mm x 50 mm) and include sensor power and output connections, and screw connections for the current to be measured.



AG940-07E: Digital/Analog/Omnipolar/Bipolar Sensor Demo Board

The kit includes a demo board with our most popular digital, analog, omnipolar, and bipolar sensors, including an AA006-00E analog sensor. Each sensor drives an indicator LED. A bar magnet is included so you can see for yourself how the sensors work. The evaluation boards are 3.75 by 5 inches (95 mm by 127 mm), and are powered by two coin cells (included).

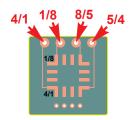


Bare Circuit Boards for Sensors

NVE offers several bare circuit boards specially designed for easy connections to surface-mount sensors. Popular PCBs are shown below (images are actual size):



AG004-06: 3" x 0.3" (75 x 8 mm) SOIC8 circuit board



AG005-06: 0.5" x 0.5" (13 mm x 13 mm) SOIC8



AG915-06: 0.25" (6 mm) octagonal MSOP8



AG918-06 (standard) / **AG919-06** (cross-axis): 2" x 0.25" (50 mm x 6 mm) MSOP8



AG035-06:

 $1.57"\ x\ 0.25"\ (40\ mm\ x\ 6\ mm)\ TDFN6$



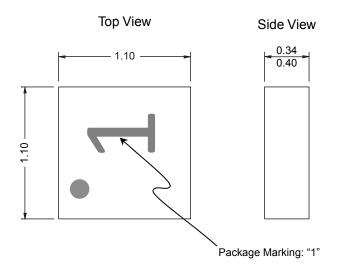
AG904-06:

1.2" x 0.25" (30 mm x 6 mm) ULLGA



Package Drawings

ULLGA4 (-14E suffix)

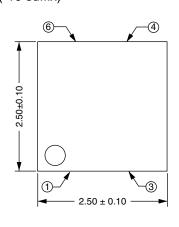


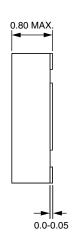
Bottom View -0.35 - 0.65 - 0.30 -0.35 - 0.65 - 0.30 -0.00 - 0.00 - 0.00 -0.00 - 0.00 - 0.

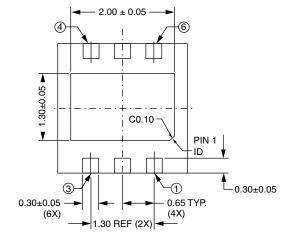
Dimensions in mm; ±0.10 mm unless otherwise noted.

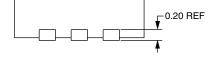
RoHS COMPLIANT

TDFN6 (-10 suffix)





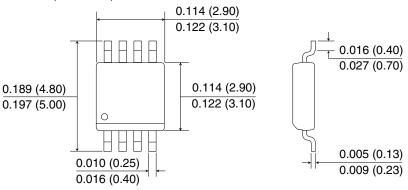


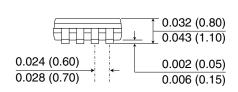






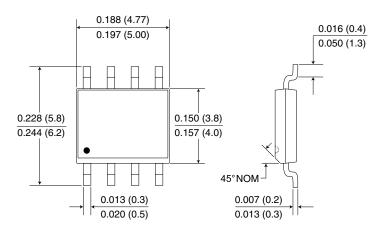
MSOP8 (-00 suffix)

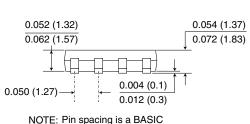




NOTE: Pin spacing is a BASIC dimension; tolerances do not accumulate

SOIC8 (-02 suffix)





dimension; tolerances
do not accumulate

Soldering profiles per JEDEC J-STD-020C, MSL 1.







Revision History

SB-00-059-E Change

January 2018 • Added Absolute Maximum isolation specification for TDFN package (p. 2).

Added TDFN Center Pad description (p. 12).

Updated AAL004 and AAL024 linearity specification (p. 13).

SB-00-059-D Change

October 2017 • Added AAK001 ultrahigh-field model.

• Added LED field-strength indicator and current-sensing applications (p. 10).

• Added AA selector chart (p. 13).

• Added Evaluation Kits (p. 14) and bare circuit boards (p. 15).

Misc. cosmetic changes and additional illustrations.

SB-00-059-C

September 2017 • Added AA007-00E high-field model.

SB-00-059-B Change

August 2017 • Added AA024-10E and AAL024-10E cross-axis versions.

SB-00-059-A Change

April 2017 • Initial datasheet release superseding catalog.





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January 2018

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