
I²C-Compatible (2-Wire) Serial EEPROM 16-Kbit (2,048 x 8)

Features

- Low-Voltage Operation:
 - $V_{CC} = 1.7V$ to $5.5V$
- Internally Organized as 2,048 x 8 (16K)
- Industrial Temperature Range: $-40^{\circ}C$ to $+85^{\circ}C$
- I²C-Compatible (2-Wire) Serial Interface:
 - 100 kHz Standard mode, 1.7V to 5.5V
 - 400 kHz Fast mode, 1.7V to 5.5V
 - 1 MHz Fast Mode Plus (FM+), 2.5V to 5.5V
- Schmitt Triggers, Filtered Inputs for Noise Suppression
- Bidirectional Data Transfer Protocol
- Write-Protect Pin for Full Array Hardware Data Protection
- Ultra Low Active Current (3 mA maximum) and Standby Current (6 μA maximum)
- 16-Byte Page Write Mode:
 - Partial page writes allowed
- Random and Sequential Read Modes
- Self-Timed Write Cycle within 5 ms Maximum
- ESD Protection > 4,000V
- High Reliability:
 - Endurance: 1,000,000 write cycles
 - Data retention: 100 years
- Green Package Options (Lead-free/Halide-free/RoHS compliant)
- Die Sale Options: Wafer Form

Packages

- 8-Lead PDIP, 8-Lead SOIC, 5-Lead SOT23, 8-Lead TSSOP, 8-Pad UDFN, 8-Pad XDFN and 8-Ball VFBGA

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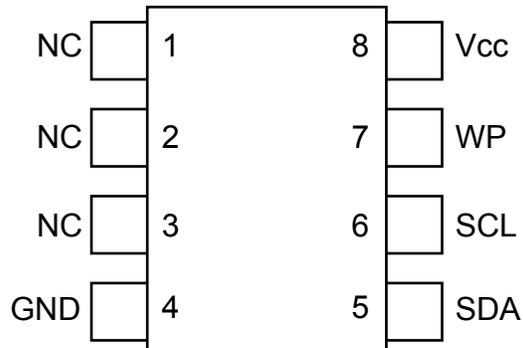
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1. Package Types (not to scale)

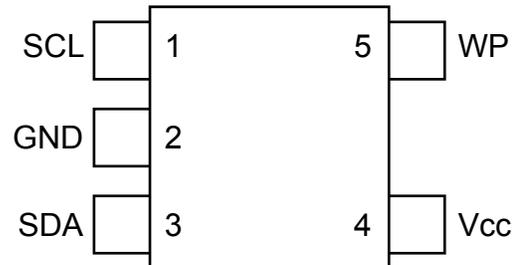
8-Lead PDIP/SOIC/TSSOP

(Top View)



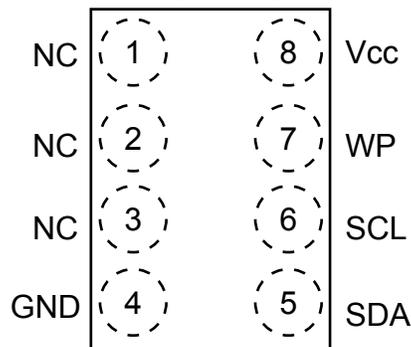
5-Lead SOT23

(Top View)



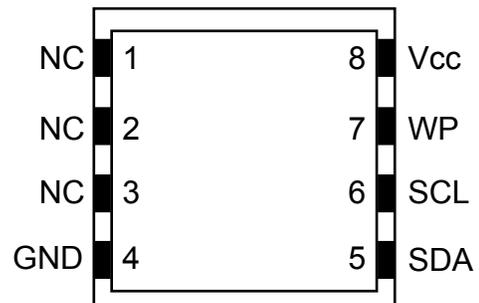
8-Ball VFBGA

(Top View)



8-Pad UDFN/XDFN

(Top View)



2. Pin Descriptions

The descriptions of the pins are listed in [Table 2-1](#).

Table 2-1. Pin Function Table

| Name | 8-Lead PDIP | 8-Lead SOIC | 8-Lead TSSOP | 5-Lead SOT23 | 8-Pad UDFN ⁽¹⁾ | 8-Ball VFBGA | 8-Pad XDFN | Function |
|-------------------|-------------|-------------|--------------|--------------|---------------------------|--------------|------------|---------------------|
| NC | 1 | 1 | 1 | — | 1 | 1 | 1 | No Connect |
| NC | 2 | 2 | 2 | — | 2 | 2 | 2 | No Connect |
| NC | 3 | 3 | 3 | — | 3 | 3 | 3 | No Connect |
| GND | 4 | 4 | 4 | 2 | 4 | 4 | 4 | Ground |
| SDA | 5 | 5 | 5 | 3 | 5 | 5 | 5 | Serial Data |
| SCL | 6 | 6 | 6 | 1 | 6 | 6 | 6 | Serial Clock |
| WP ⁽²⁾ | 7 | 7 | 7 | 5 | 7 | 7 | 7 | Write-Protect |
| V _{CC} | 8 | 8 | 8 | 4 | 8 | 8 | 8 | Device Power Supply |

Note:

1. The exposed pad on this package can be connected to GND or left floating.
2. If the WP pin is not driven, it is internally pulled down to GND. In order to operate in a wide variety of application environments, the pull-down mechanism is intentionally designed to be somewhat strong. Once this pin is biased above the CMOS input buffer's trip point ($\sim 0.5 \times V_{CC}$), the pull-down mechanism disengages. Microchip recommends connecting this pin to a known state whenever possible.

2.1 Ground

The ground reference for the power supply. GND should be connected to the system ground.

2.2 Serial Data (SDA)

The SDA pin is an open-drain bidirectional input/output pin used to serially transfer data to and from the device. The SDA pin must be pulled-high using an external pull-up resistor (not to exceed 10 kΩ in value) and may be wire-ORed with any number of other open-drain or open-collector pins from other devices on the same bus.

2.3 Serial Clock (SCL)

The SCL pin is used to provide a clock to the device and to control the flow of data to and from the device. Command and input data present on the SDA pin is always latched in on the rising edge of SCL, while output data on the SDA pin is clocked out on the falling edge of SCL. The SCL pin must either be forced high when the serial bus is idle or pulled high using an external pull-up resistor.

2.4 Write-Protect (WP)

The write-protect input, when connected to GND, allows normal write operations. When the WP pin is connected directly to V_{CC}, all write operations to the protected memory are inhibited.

If the pin is left floating, the WP pin will be internally pulled down to GND. However, due to capacitive coupling that may appear in customer applications, Microchip recommends always connecting the WP pin to a known state. When using a pull-up resistor, Microchip recommends using 10 kΩ or less.

Table 2-2. Write-Protect

| WP Pin Status | Part of the Array Protected |
|----------------------|------------------------------------|
| At V _{CC} | Full Array |
| At GND | Normal Write Operations |

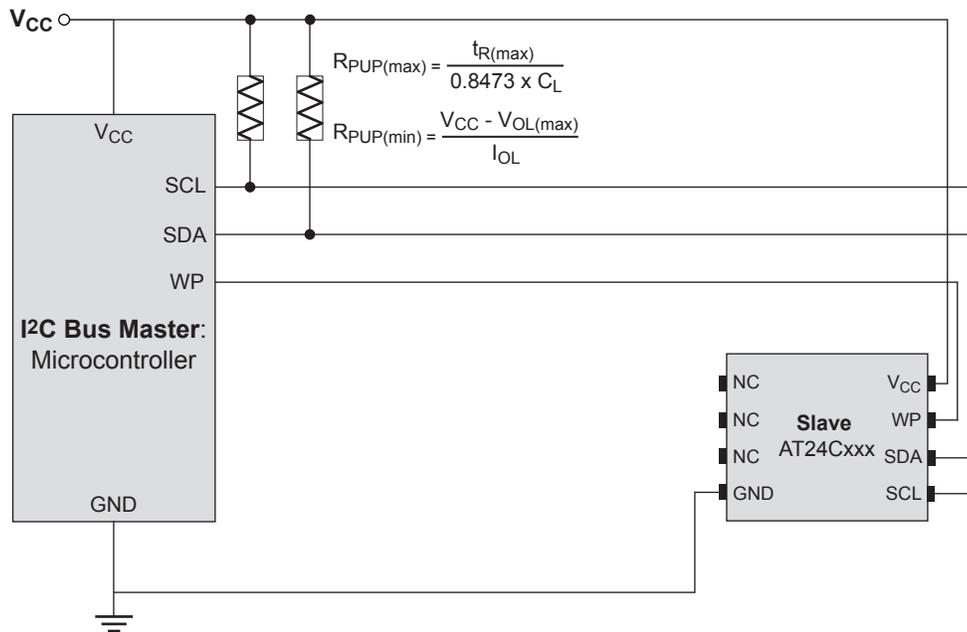
2.5 Device Power Supply

The V_{CC} pin is used to supply the source voltage to the device. Operations at invalid V_{CC} voltages may produce spurious results and should not be attempted.

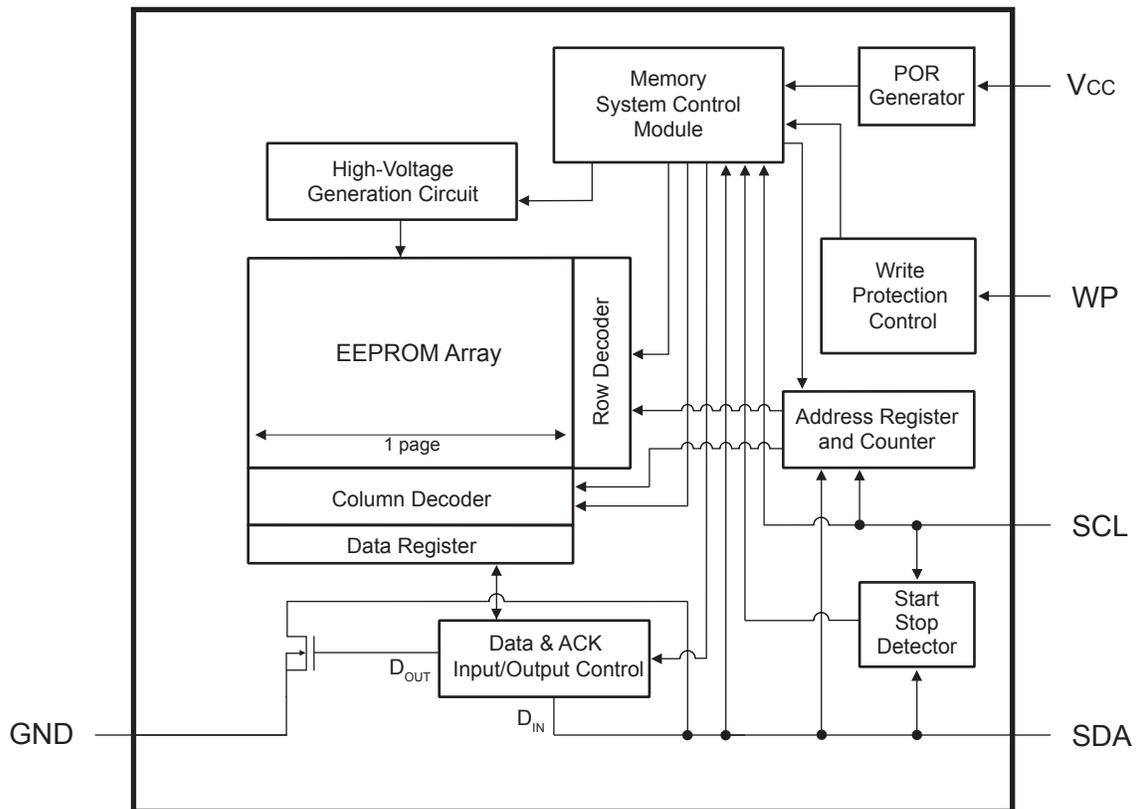
3. Description

The AT24C16C provides 16,384 bits of Serial Electrically Erasable and Programmable Read-Only Memory (EEPROM) organized as 2,048 words of 8 bits each. This device is optimized for use in many industrial and commercial applications where low-power and low-voltage operations are essential. The device is available in space-saving 8-lead SOIC, 8-lead TSSOP, 8-pad UDFN, 8-lead PDIP, 5-lead SOT23, 8-ball VFBGA and 8-pad XDFN packages. All packages operate from 1.7V to 5.5V.

3.1 System Configuration Using 2-Wire Serial EEPROMs



3.2 Block Diagram



4. Electrical Characteristics

4.1 Absolute Maximum Ratings

| | |
|---|-----------------|
| Temperature under bias | -55°C to +125°C |
| Storage temperature | -65°C to +150°C |
| V _{CC} | 6.25V |
| Voltage on any pin with respect to ground | -1.0V to +7.0V |
| DC output current | 5.0 mA |
| ESD protection | >4 kV |

Note: Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operation listings of this specification are not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

4.2 DC and AC Operating Range

Table 4-1. DC and AC Operating Range

| AT24C16C | | |
|------------------------------|------------------------------|----------------|
| Operating Temperature (Case) | Industrial Temperature Range | -40°C to +85°C |
| V _{CC} Power Supply | Low Voltage Grade | 1.7V to 5.5V |

4.3 DC Characteristics

Table 4-2. DC Characteristics

| Parameter | Symbol | Minimum | Typical ⁽¹⁾ | Maximum | Units | Test Conditions |
|-----------------|------------------|---------|------------------------|---------|-------|--|
| Supply Voltage | V _{CC} | 1.7 | — | 5.5 | V | |
| Supply Current | I _{CC1} | — | 0.4 | 1.0 | mA | V _{CC} = 5.0V, Read at 100 kHz |
| Supply Current | I _{CC2} | — | 2.0 | 3.0 | mA | V _{CC} = 5.0V, Write at 100 kHz |
| Standby Current | I _{SB} | — | — | 1.0 | μA | V _{CC} = 1.7V, V _{IN} = V _{CC} or GND |
| | | — | — | 6.0 | μA | V _{CC} = 5.5V, V _{IN} = V _{CC} or GND |

AT24C16C

Electrical Characteristics

| Parameter | Symbol | Minimum | Typical ⁽¹⁾ | Maximum | Units | Test Conditions |
|------------------------|-----------|---------------------|------------------------|---------------------|---------------|--|
| Input Leakage Current | I_{LI} | — | 0.10 | 3.0 | μA | $V_{IN} = V_{CC}$ or GND |
| Output Leakage Current | I_{LO} | — | 0.05 | 3.0 | μA | $V_{OUT} = V_{CC}$ or GND |
| Input Low Level | V_{IL} | -0.6 | — | $V_{CC} \times 0.3$ | V | Note 2 |
| Input High Level | V_{IH} | $V_{CC} \times 0.7$ | — | $V_{CC} + 0.5$ | V | Note 2 |
| Output Low Level | V_{OL1} | — | — | 0.2 | V | $V_{CC} = 1.7\text{V}$, $I_{OL} = 0.15\text{ mA}$ |
| Output Low Level | V_{OL2} | — | — | 0.4 | V | $V_{CC} = 3.0\text{V}$, $I_{OL} = 2.1\text{ mA}$ |

Note:

1. Typical values characterized at $T_A = +25^\circ\text{C}$ unless otherwise noted.
2. This parameter is characterized but is not 100% tested in production.

4.4 AC Characteristics

Table 4-3. AC Characteristics⁽¹⁾

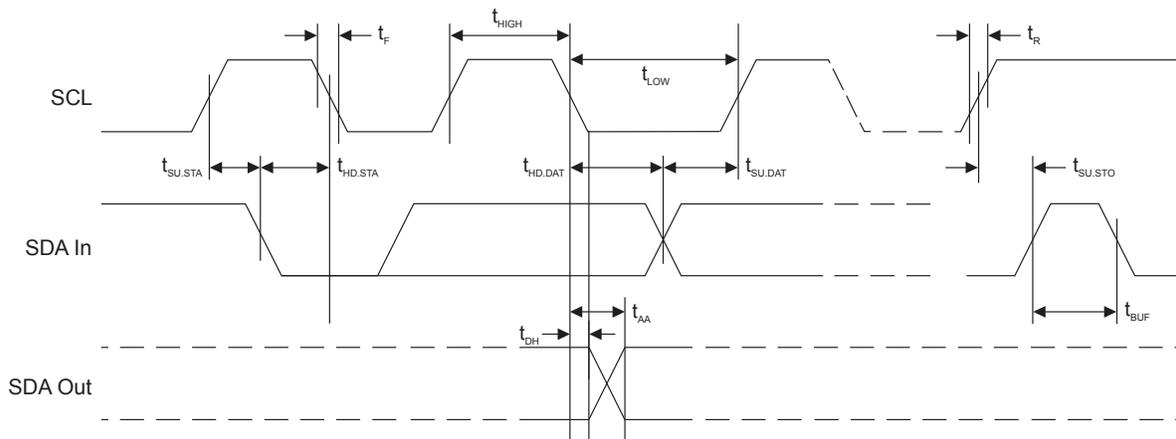
| Parameter | Symbol | 1.7V | | 2.5V, 2.7V, 5.0V | | Units |
|--------------------------------------|--------------|-------|------|------------------|------|-------|
| | | Min. | Max. | Min. | Max. | |
| Clock Frequency, SCL | f_{SCL} | — | 400 | — | 1000 | kHz |
| Clock Pulse Width Low | t_{LOW} | 1,200 | — | 500 | — | ns |
| Clock Pulse Width High | t_{HIGH} | 600 | — | 400 | — | ns |
| Input Filter Spike Suppression | t_I | — | 100 | — | 50 | ns |
| Clock Low to Data Out Valid | t_{AA} | 100 | 900 | 50 | 450 | ns |
| Bus Free Time between Stop and Start | t_{BUF} | 1,200 | — | 500 | — | ns |
| Start Hold Time | $t_{HD.STA}$ | 600 | — | 250 | — | ns |
| Start Set-Up Time | $t_{SU.STA}$ | 600 | — | 250 | — | ns |
| Data In Hold Time | $t_{HD.DAT}$ | 0 | — | 0 | — | ns |
| Data In Set-up Time | $t_{SU.DAT}$ | 100 | — | 100 | — | ns |

| Parameter | Symbol | 1.7V | | 2.5V, 2.7V, 5.0V | | Units |
|---------------------------------|--------------|------|------|------------------|------|-------|
| | | Min. | Max. | Min. | Max. | |
| Inputs Rise Time ⁽²⁾ | t_R | — | 300 | — | 300 | ns |
| Inputs Fall Time ⁽²⁾ | t_F | — | 300 | — | 100 | ns |
| Stop Set-Up Time | $t_{SU.STO}$ | 600 | — | 250 | — | ns |
| Data Out Hold Time | t_{DH} | 50 | — | 50 | — | ns |
| Write Cycle Time | t_{WR} | — | 5 | — | 5 | ms |

Note:

- AC measurement conditions:
 - C_L : 100 pF
 - R_{PUP} (SDA bus line pull-up resistor to V_{CC}): 1.3 k Ω (1000 kHz), 4 k Ω (400 kHz), 10 k Ω (100 kHz)
 - Input rise and fall times: ≤ 50 ns
 - Input and output timing reference voltages: $0.5 \times V_{CC}$
- These parameters are determined through product characterization and are not 100% tested in production.

Figure 4-1. Bus Timing



4.5 Electrical Specifications

4.5.1 Power-Up Requirements and Reset Behavior

During a power-up sequence, the V_{CC} supplied to the AT24C16C should monotonically rise from GND to the minimum V_{CC} level, as specified in [Table 4-1](#), with a slew rate no faster than 0.1 V/ μ s.

4.5.1.1 Device Reset

To prevent inadvertent write operations or any other spurious events from occurring during a power-up sequence, the AT24C16C includes a Power-on Reset (POR) circuit. Upon power-up, the device will not respond to any commands until the V_{CC} level crosses the internal voltage threshold (V_{POR}) that brings the device out of Reset and into Standby mode.

The system designer must ensure the instructions are not sent to the device until the V_{CC} supply has reached a stable value greater than or equal to the minimum V_{CC} level. Additionally, once the V_{CC} is greater than or equal to the minimum V_{CC} level, the bus master must wait at least t_{PUP} before sending the first command to the device. See [Table 4-4](#) for the values associated with these power-up parameters.

Table 4-4. Power-up Conditions⁽¹⁾

| Symbol | Parameter | Min. | Max. | Units |
|------------|--|------|------|---------|
| t_{PUP} | Time required after V_{CC} is stable before the device can accept commands | 100 | — | μ s |
| V_{POR} | Power-on Reset Threshold Voltage | — | 1.5 | V |
| t_{POFF} | Minimum time at $V_{CC} = 0V$ between power cycles | 500 | — | ms |

Note:

- These parameters are characterized but they are not 100% tested in production.

If an event occurs in the system where the V_{CC} level supplied to the AT24C16C drops below the maximum V_{POR} level specified, it is recommended that a full power cycle sequence be performed by first driving the V_{CC} pin to GND, waiting at least the minimum t_{POFF} time and then performing a new power-up sequence in compliance with the requirements defined in this section.

4.5.2 Pin Capacitance

Table 4-5. Pin Capacitance⁽¹⁾

| Symbol | Test Condition | Max. | Units | Conditions |
|-----------|--------------------------------|------|-------|----------------|
| $C_{I/O}$ | Input/Output Capacitance (SDA) | 8 | pF | $V_{I/O} = 0V$ |
| C_{IN} | Input Capacitance (SCL) | 6 | pF | $V_{IN} = 0V$ |

Note:

- This parameter is characterized but is not 100% tested in production.

4.5.3 EEPROM Cell Performance Characteristics

Table 4-6. EEPROM Cell Performance Characteristics

| Operation | Test Condition | Min. | Max. | Units |
|--------------------------------|---|-----------|------|--------------|
| Write Endurance ⁽¹⁾ | $T_A = 25^\circ C$, $V_{CC} = 3.3V$, Page Write mode | 1,000,000 | — | Write Cycles |
| Data Retention ⁽¹⁾ | $T_A = 55^\circ C$ | 100 | — | Years |

Note:

- Performance is determined through characterization and the qualification process.

5. Device Operation and Communication

The AT24C16C operates as a slave device and utilizes a simple I²C-compatible 2-wire digital serial interface to communicate with a host controller, commonly referred to as the bus master. The master initiates and controls all read and write operations to the slave devices on the serial bus, and both the master and the slave devices can transmit and receive data on the bus.

The serial interface is comprised of just two signal lines: Serial Clock (SCL) and Serial Data (SDA). The SCL pin is used to receive the clock signal from the master, while the bidirectional SDA pin is used to receive command and data information from the master as well as to send data back to the master. Data is always latched into the AT24C16C on the rising edge of SCL and always output from the device on the falling edge of SCL. Both the SCL and SDA pin incorporate integrated spike suppression filters and Schmitt Triggers to minimize the effects of input spikes and bus noise.

All command and data information is transferred with the Most Significant bit (MSb) first. During bus communication, one data bit is transmitted every clock cycle, and after eight bits (one byte) of data have been transferred, the receiving device must respond with either an Acknowledge (ACK) or a No-Acknowledge (NACK) response bit during a ninth clock cycle (ACK/NACK clock cycle) generated by the master. Therefore, nine clock cycles are required for every one byte of data transferred. There are no unused clock cycles during any read or write operation, so there must not be any interruptions or breaks in the data stream during each data byte transfer and ACK or NACK clock cycle.

During data transfers, data on the SDA pin must only change while SCL is low, and the data must remain stable while SCL is high. If data on the SDA pin changes while SCL is high, then either a Start or a Stop condition will occur. Start and Stop conditions are used to initiate and end all serial bus communication between the master and the slave devices. The number of data bytes transferred between a Start and a Stop condition is not limited and is determined by the master. In order for the serial bus to be idle, both the SCL and SDA pins must be in the logic-high state at the same time.

5.1 Clock and Data Transition Requirements

The SDA pin is an open-drain terminal and therefore must be pulled high with an external pull-up resistor. SCL is an input pin that can either be driven high or pulled high using an external pull-up resistor. Data on the SDA pin may change only during SCL low time periods. Data changes during SCL high periods will indicate a Start or Stop condition as defined below. The relationship of the AC timing parameters with respect to SCL and SDA for the AT24C16C are shown in the timing waveform in [Figure 4-1](#). The AC timing characteristics and specifications are outlined in [4.4 AC Characteristics](#).

5.2 Start and Stop Conditions

5.2.1 Start Condition

A Start condition occurs when there is a high-to-low transition on the SDA pin while the SCL pin is at a stable logic '1' state and will bring the device out of Standby mode. The master uses a Start condition to initiate any data transfer sequence; therefore, every command must begin with a Start condition. The device will continuously monitor the SDA and SCL pins for a Start condition but will not respond unless one is detected. Refer to [Figure 5-1](#) for more details.

5.2.2 Stop Condition

A Stop condition occurs when there is a low-to-high transition on the SDA pin while the SCL pin is stable in the logic '1' state.

The master can use the Stop condition to end a data transfer sequence with the AT24C16C, which will subsequently return to Standby mode. The master can also utilize a repeated Start condition instead of a Stop condition to end the current data transfer if the master will perform another operation. Refer to [Figure 5-1](#) for more details.

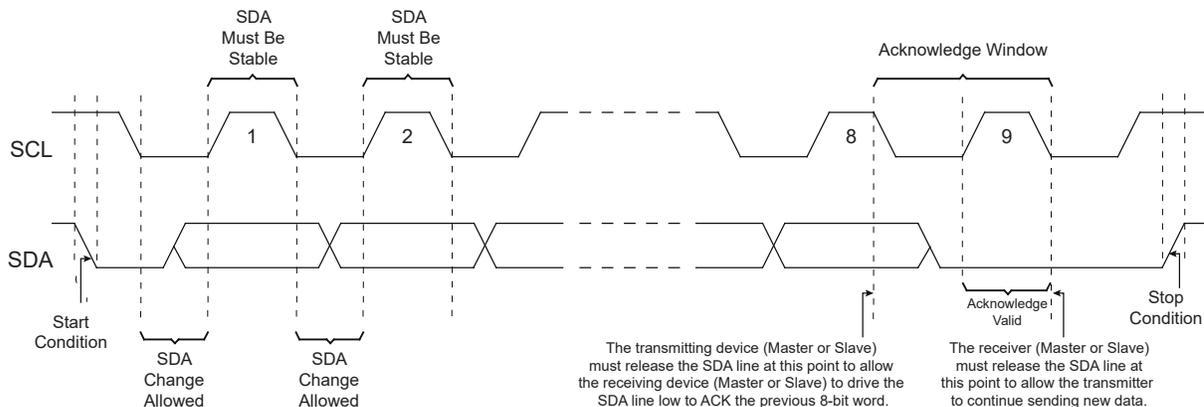
5.3 Acknowledge and No-Acknowledge

After every byte of data is received, the receiving device must confirm to the transmitting device that it has successfully received the data byte by responding with what is known as an Acknowledge (ACK). An ACK is accomplished by the transmitting device first releasing the SDA line at the falling edge of the eighth clock cycle followed by the receiving device responding with a logic '0' during the entire high period of the ninth clock cycle.

When the AT24C16C is transmitting data to the master, the master can indicate that it is done receiving data and wants to end the operation by sending a logic '1' response to the AT24C16C instead of an ACK response during the ninth clock cycle. This is known as a No-Acknowledge (NACK) and is accomplished by the master sending a logic '1' during the ninth clock cycle, at which point the AT24C16C will release the SDA line so the master can then generate a Stop condition.

The transmitting device, which can be the bus master or the Serial EEPROM, must release the SDA line at the falling edge of the eighth clock cycle to allow the receiving device to drive the SDA line to a logic '0' to ACK the previous 8-bit word. The receiving device must release the SDA line at the end of the ninth clock cycle to allow the transmitter to continue sending new data. A timing diagram has been provided in [Figure 5-1](#) to better illustrate these requirements.

Figure 5-1. Start Condition, Data Transitions, Stop Condition and Acknowledge



5.4 Standby Mode

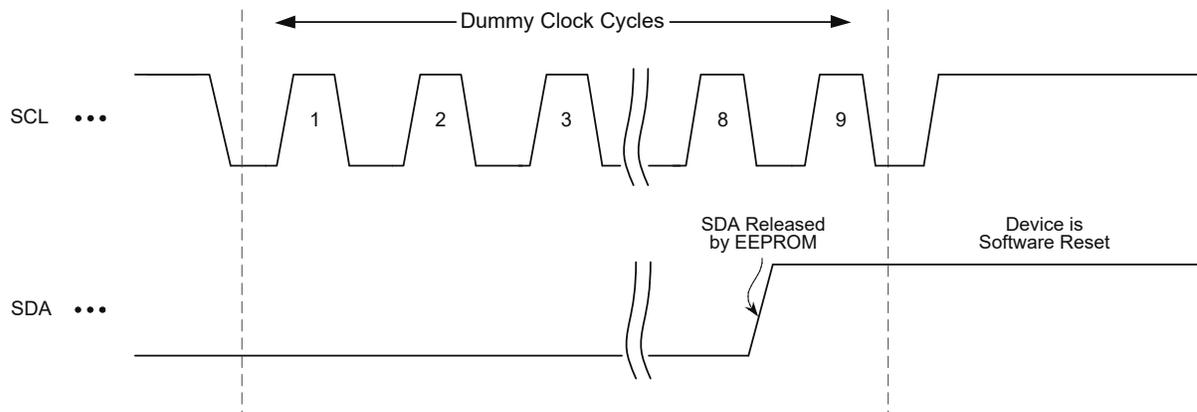
The AT24C16C features a low-power Standby mode that is enabled when any one of the following occurs:

- A valid power-up sequence is performed (see [4.5.1 Power-Up Requirements and Reset Behavior](#)).
- A Stop condition is received by the device unless it initiates an internal write cycle (see [7. Write Operations](#)).
- At the completion of an internal write cycle (see [7. Write Operations](#)).

5.5 Software Reset

After an interruption in protocol, power loss or system Reset, any 2-wire device can be protocol reset by clocking SCL until SDA is released by the EEPROM and goes high. The number of clock cycles until SDA is released by the EEPROM will vary. The software Reset sequence should not take more than nine dummy clock cycles. Once the software Reset sequence is complete, new protocol can be sent to the device by sending a Start condition followed by the protocol. Refer to [Figure 5-2](#) for an illustration.

Figure 5-2. Software Reset



In the event that the device is still non-responsive or remains active on the SDA bus, a power cycle must be used to reset the device (see [4.5.1 Power-Up Requirements and Reset Behavior](#)).

6. Memory Organization

The AT24C16C is internally organized as 128 pages of 16 bytes each.

6.1 Device Addressing

Accessing the device requires an 8-bit device address byte following a Start condition to enable the device for a read or write operation.

The Most Significant four bits of the device address byte is referred to as the device type identifier. The device type identifier '1010' (Ah) is required in bits 7 through 4 of the device address byte (see [Table 6-1](#)).

Following the 4-bit device type identifier in the bit 3, bit 2 and bit 1 position of the device address byte are bits A10, A9 and A8 which are the three Most Significant bits of the memory array word address.

The eighth bit (bit 0) of the device address byte is the Read/Write Select bit. A read operation is initiated if this bit is high and a write operation is initiated if this bit is low.

Upon the successful comparison of the device address byte, the AT24C16C will return an ACK. If a valid comparison is not made, the device will NACK.

Table 6-1. Device Address Byte

| Package | Device Type Identifier | | | | Most Significant Bits of the Word Address | | | R/W Select |
|-------------------|------------------------|-------|-------|-------|---|-------|-------|------------|
| | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| All Package Types | 1 | 0 | 1 | 0 | A10 | A9 | A8 | R/W |

For all operations except the current address read, a word address byte must be transmitted to the device immediately following the device address byte. The word address byte consists of the remaining eight bits of the 11-bit memory array word address, and is used to specify which byte location in the EEPROM to start reading or writing. Refer to [Table 6-2](#) to review these bit positions.

Table 6-2. Word Address Byte

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| A7 | A6 | A5 | A4 | A3 | A2 | A1 | A0 |

7. Write Operations

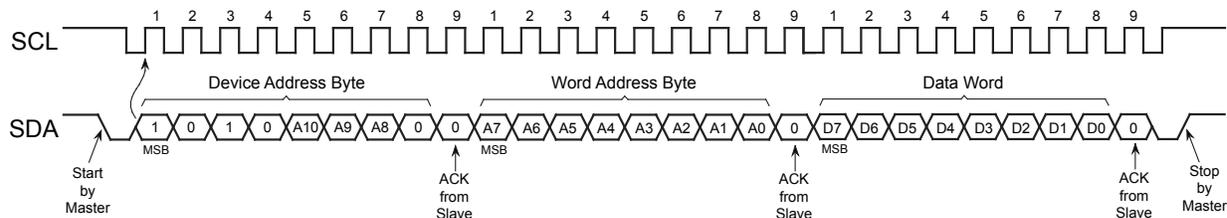
All write operations for the AT24C16C begin with the master sending a Start condition, followed by a device address byte with the R/W bit set to logic '0', and then by the word address byte. The data value(s) to be written to the device immediately follow the word address byte.

7.1 Byte Write

The AT24C16C supports the writing of a single 8-bit byte. Selecting a data word in the AT24C16C requires an 11-bit word address.

Upon receipt of the proper device address and the word address bytes, the EEPROM will send an Acknowledge. The device will then be ready to receive the 8-bit data word. Following receipt of the 8-bit data word, the EEPROM will respond with an ACK. The addressing device, such as a bus master, must then terminate the write operation with a Stop condition. At that time, the EEPROM will enter an internally self-timed write cycle, which will be completed within t_{WR} , while the data word is being programmed into the nonvolatile EEPROM. All inputs are disabled during this write cycle, and the EEPROM will not respond until the write is complete.

Figure 7-1. Byte Write



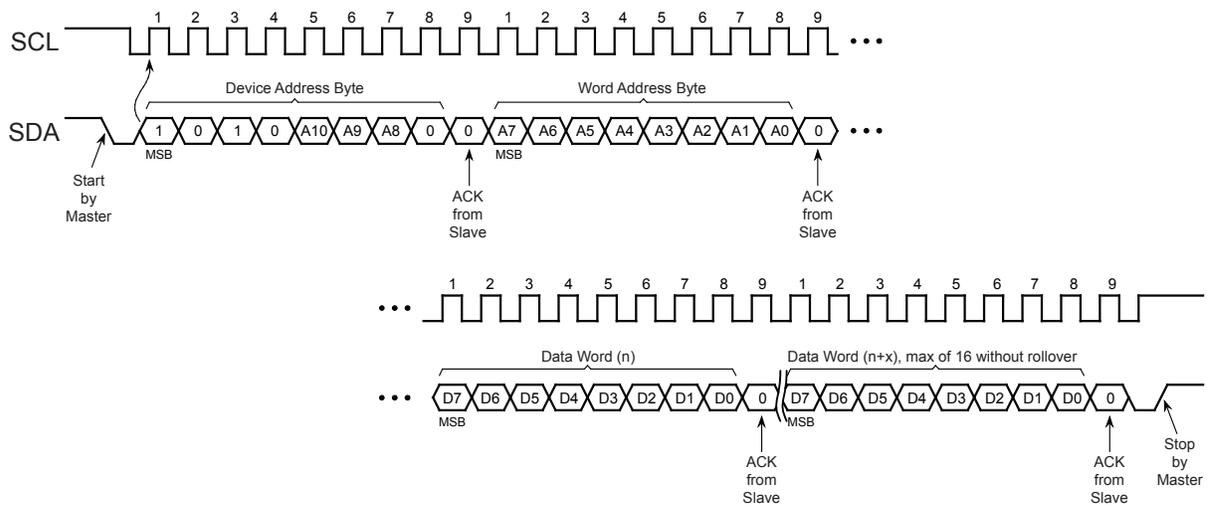
7.2 Page Write

A page write operation allows up to 16 bytes to be written in the same write cycle, provided all bytes are in the same row of the memory array (where address bits A10 through A4 are the same). Partial page writes of less than 16 bytes are also allowed.

A page write is initiated the same way as a byte write, but the bus master does not send a Stop condition after the first data word is clocked in. Instead, after the EEPROM acknowledges receipt of the first data word, the bus master can transmit up to fifteen additional data words. The EEPROM will respond with an ACK after each data word is received. Once all data to be written has been sent to the device, the bus master must issue a Stop condition (see [Figure 7-2](#)) at which time the internally self-timed write cycle will begin.

The lower four bits of the word address are internally incremented following the receipt of each data word. The higher order address bits are not incremented and retain the memory page row location. Page write operations are limited to writing bytes within a single physical page, regardless of the number of bytes actually being written. When the incremented word address reaches the page boundary, the address counter will roll-over to the beginning of the same page. Nevertheless, creating a roll-over event should be avoided as previously loaded data in the page could become unintentionally altered.

Figure 7-2. Page Write

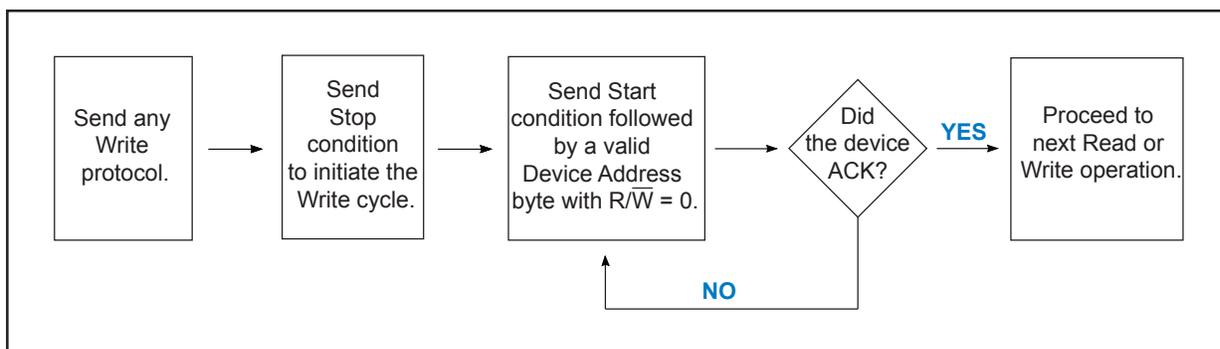


7.3 Acknowledge Polling

An Acknowledge Polling routine can be implemented to optimize time-sensitive applications that would prefer not to wait the fixed maximum write cycle time (t_{WR}). This method allows the application to know immediately when the Serial EEPROM write cycle has completed, so a subsequent operation can be started.

Once the internally self-timed write cycle has started, an Acknowledge Polling routine can be initiated. This involves repeatedly sending a Start condition followed by a valid device address byte with the R/W bit set at logic '0'. The device will not respond with an ACK while the write cycle is ongoing. Once the internal write cycle has completed, the EEPROM will respond with an ACK, allowing a new read or write operation to be immediately initiated. A flowchart has been included below in [Figure 7-3](#) to better illustrate this technique.

Figure 7-3. Acknowledge Polling Flowchart

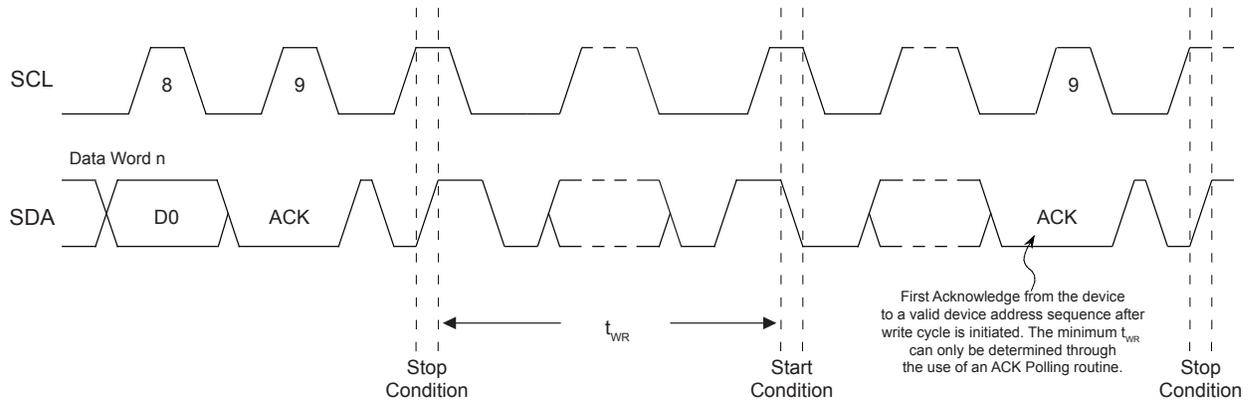


7.4 Write Cycle Timing

The length of the self-timed write cycle (t_{WR}) is defined as the amount of time from the Stop condition that begins the internal write cycle to the Start condition of the first device address byte sent to the AT24C16C that it subsequently responds to with an ACK. [Figure 7-4](#) has been included to show this measurement.

During the internally self-timed write cycle, any attempts to read from or write to the memory array will not be processed.

Figure 7-4. Write Cycle Timing



7.5 Write Protection

The AT24C16C utilizes a hardware data protection scheme that allows the user to write-protect the entire memory contents when the WP pin is at V_{CC} (or a valid V_{IH}). No write protection will be set if the WP pin is at GND or left floating.

Table 7-1. AT24C16C Write-Protect Behavior

| WP Pin Voltage | Part of the Array Protected |
|----------------|-------------------------------------|
| V_{CC} | Full Array |
| GND | None — Write Protection Not Enabled |

The status of the WP pin is sampled at the Stop condition for every byte write or page write operation prior to the start of an internally self-timed write cycle. Changing the WP pin state after the Stop condition has been sent will not alter or interrupt the execution of the write cycle.

If an attempt is made to write to the device while the WP pin has been asserted, the device will acknowledge the device address, word address and data bytes, but no write cycle will occur when the Stop condition is issued. The device will immediately be ready to accept a new read or write command.

8. Read Operations

Read operations are initiated the same way as write operations with the exception that the Read/Write Select bit in the device address byte must be a logic '1'. There are three read operations:

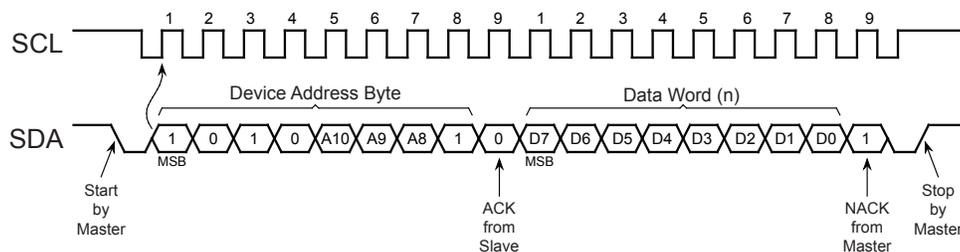
- Current Address Read
- Random Address Read
- Sequential Read

8.1 Current Address Read

The internal data word address counter maintains the last address accessed during the last read or write operation, incremented by one. This address stays valid between operations as long as the V_{CC} is maintained to the part. The address roll-over during a read is from the last byte of the last page to the first byte of the first page of the memory.

A current address read operation will output data according to the location of the internal data word address counter. This is initiated with a Start condition, followed by a valid device address byte with the R/\overline{W} bit set to logic '1'. The device will ACK this sequence and the current address data word is serially clocked out on the SDA line. All types of read operations will be terminated if the bus master does not respond with an ACK (it NACKs) during the ninth clock cycle. After the NACK response, the master may send a Stop condition to complete the protocol, or it can send a Start condition to begin the next sequence.

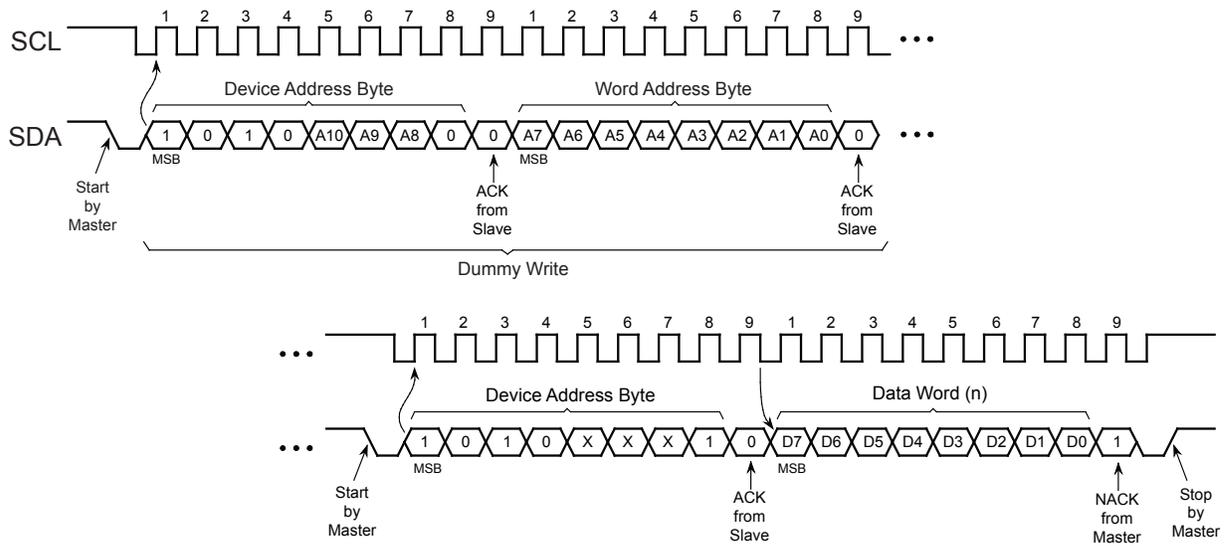
Figure 8-1. Current Address Read



8.2 Random Read

A random read begins in the same way as a byte write operation does to load in a new data word address. This is known as a “dummy write” sequence; however, the data byte and the Stop condition of the byte write must be omitted to prevent the part from entering an internal write cycle. Once the device address and word address are clocked in and acknowledged by the EEPROM, the bus master must generate another Start condition. The bus master now initiates a current address read by sending a Start condition, followed by a valid device address byte with the R/\overline{W} bit set to logic '1'. In this second device address byte, the bit positions usually reserved for the Most Significant bits of the word address (bit 3, 2 and 1) are "don't care" bits since the address that will be read from is determined only by what was sent in the dummy write portion of the sequence. The EEPROM will ACK the device address and serially clock out the data word on the SDA line. All types of read operations will be terminated if the bus master does not respond with an ACK (it NACKs) during the ninth clock cycle. After the NACK response, the master may send a Stop condition to complete the protocol, or it can send a Start condition to begin the next sequence.

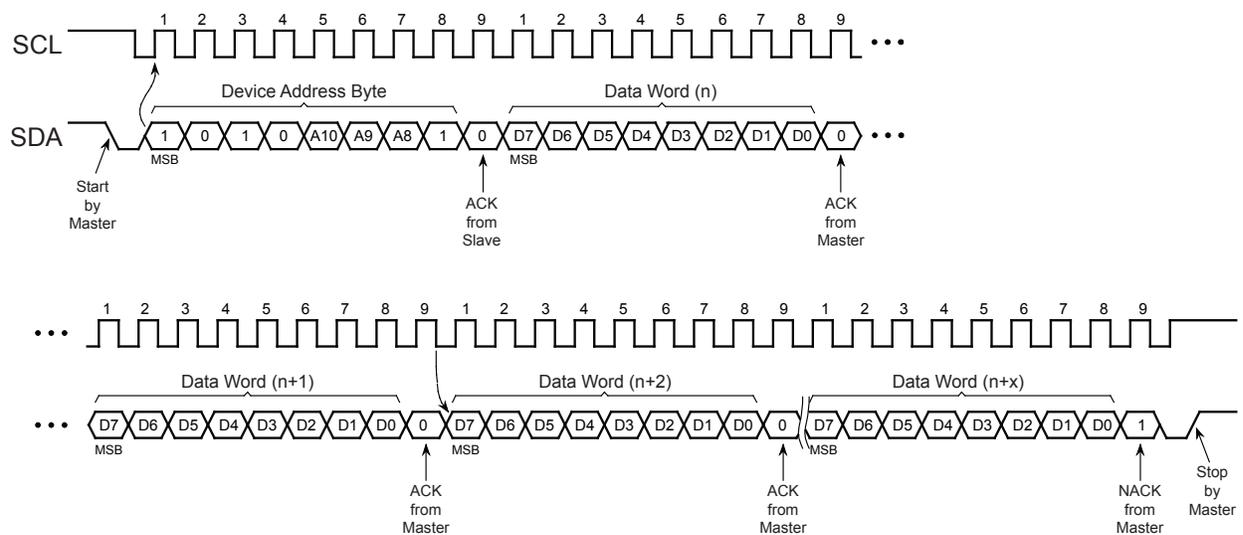
Figure 8-2. Random Read



8.3 Sequential Read

Sequential reads are initiated by either a current address read or a random read. After the bus master receives a data word, it responds with an Acknowledge. As long as the EEPROM receives an ACK, it will continue to increment the word address and serially clock out sequential data words. When the maximum memory address is reached, the data word address will roll-over and the sequential read will continue from the beginning of the memory array. All types of read operations will be terminated if the bus master does not respond with an ACK (it NACKs) during the ninth clock cycle. After the NACK response, the master may send a Stop condition to complete the protocol, or it can send a Start condition to begin the next sequence.

Figure 8-3. Sequential Read



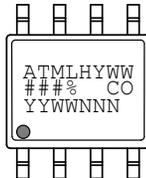
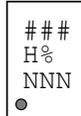
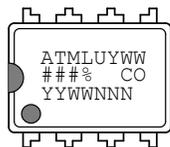
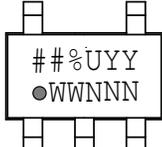
9. Device Default Condition from Microchip

The AT24C16C is delivered with the EEPROM array set to logic '1', resulting in FFh data in all locations.

10. Packaging Information

10.1 Package Marking Information

AT24C16C: Package Marking Information

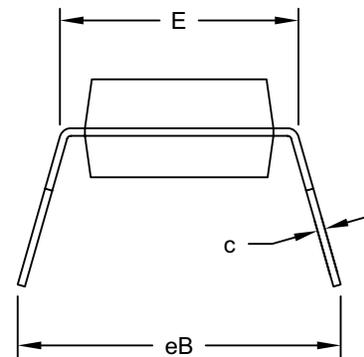
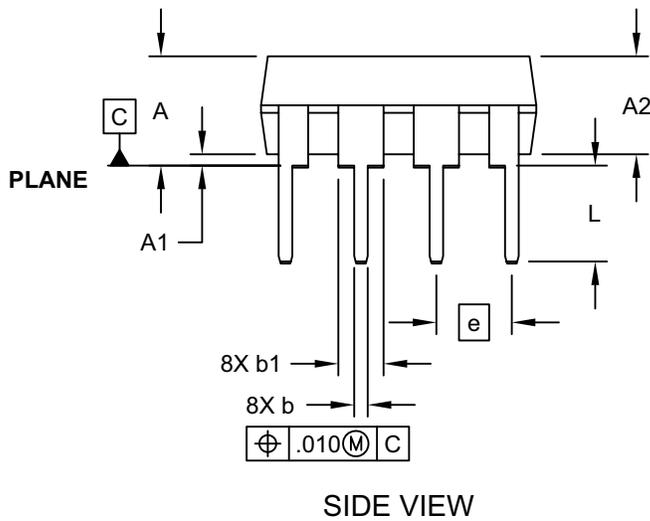
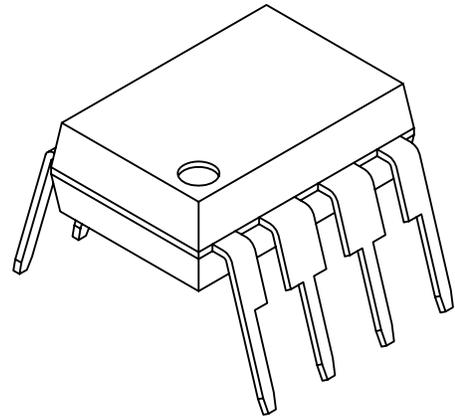
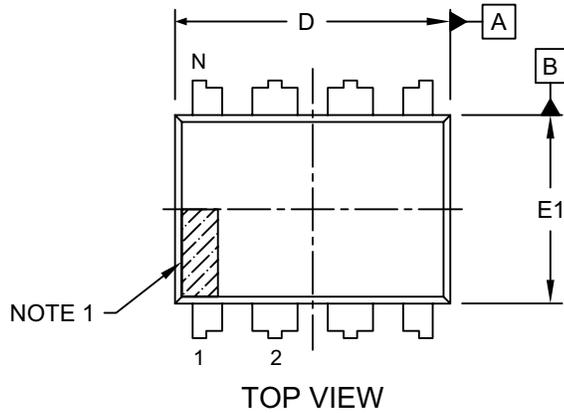
| | | | |
|---|--|---|---|
| 8-lead SOIC  | 8-lead TSSOP  | 8-pad UDFN 2.0 x 3.0 mm Body  | 8-pad XDFN 1.8 x 2.2 mm Body  |
| 8-lead PDIP  | 5-lead SOT23  | 8-ball VFBGA 1.5 x 2.0 mm Body  | |

Note 1: ● designates pin 1
 Note 2: Package drawings are not to scale
 Note 3: For SOT23 package with date codes before 7B, the bottom line (YYMMXX) is marked on the bottom side and there is no Country of Assembly (@) mark on the top line.

| Catalog Number Truncation | | | |
|---|--------------------|-----------------------------------|---------------------|
| AT24C16C | | Truncation Code ###: 16C / ##: AC | |
| Date Codes | | Voltages | |
| YY = Year | Y = Year | WW = Work Week of Assembly | % = Minimum Voltage |
| 16: 2016 20: 2020 | 6: 2016 0: 2020 | 02: Week 2 | M: 1.7V min |
| 17: 2017 21: 2021 | 7: 2017 1: 2021 | 04: Week 4 | |
| 18: 2018 22: 2022 | 8: 2018 2: 2022 | ... | |
| 19: 2019 23: 2023 | 9: 2019 3: 2023 | 52: Week 52 | |
| Country of Origin | | Device Grade | |
| CO = Country of Origin | | H or U: Industrial Grade | |
| Atmel Truncation | | | |
| AT: Atmel ATM: Atmel ATML: Atmel | | | |
| Trace Code | | | |
| NNN = Alphanumeric Trace Code (2 Characters for Small Packages) | | | |

8-Lead Plastic Dual In-Line (P) - 300 mil Body [PDIP]

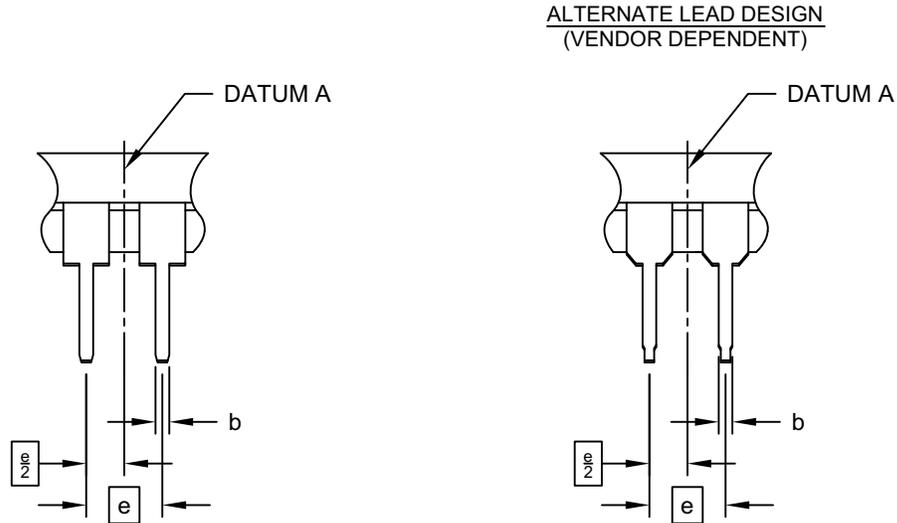
Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing No. C04-018D Sheet 1 of 2

8-Lead Plastic Dual In-Line (P) - 300 mil Body [PDIP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



| Dimension Limits | Units | INCHES | | |
|----------------------------|-------|----------|------|------|
| | | MIN | NOM | MAX |
| Number of Pins | N | 8 | | |
| Pitch | e | .100 BSC | | |
| Top to Seating Plane | A | - | - | .210 |
| Molded Package Thickness | A2 | .115 | .130 | .195 |
| Base to Seating Plane | A1 | .015 | - | - |
| Shoulder to Shoulder Width | E | .290 | .310 | .325 |
| Molded Package Width | E1 | .240 | .250 | .280 |
| Overall Length | D | .348 | .365 | .400 |
| Tip to Seating Plane | L | .115 | .130 | .150 |
| Lead Thickness | c | .008 | .010 | .015 |
| Upper Lead Width | b1 | .040 | .060 | .070 |
| Lower Lead Width | b | .014 | .018 | .022 |
| Overall Row Spacing | § eB | - | - | .430 |

Notes:

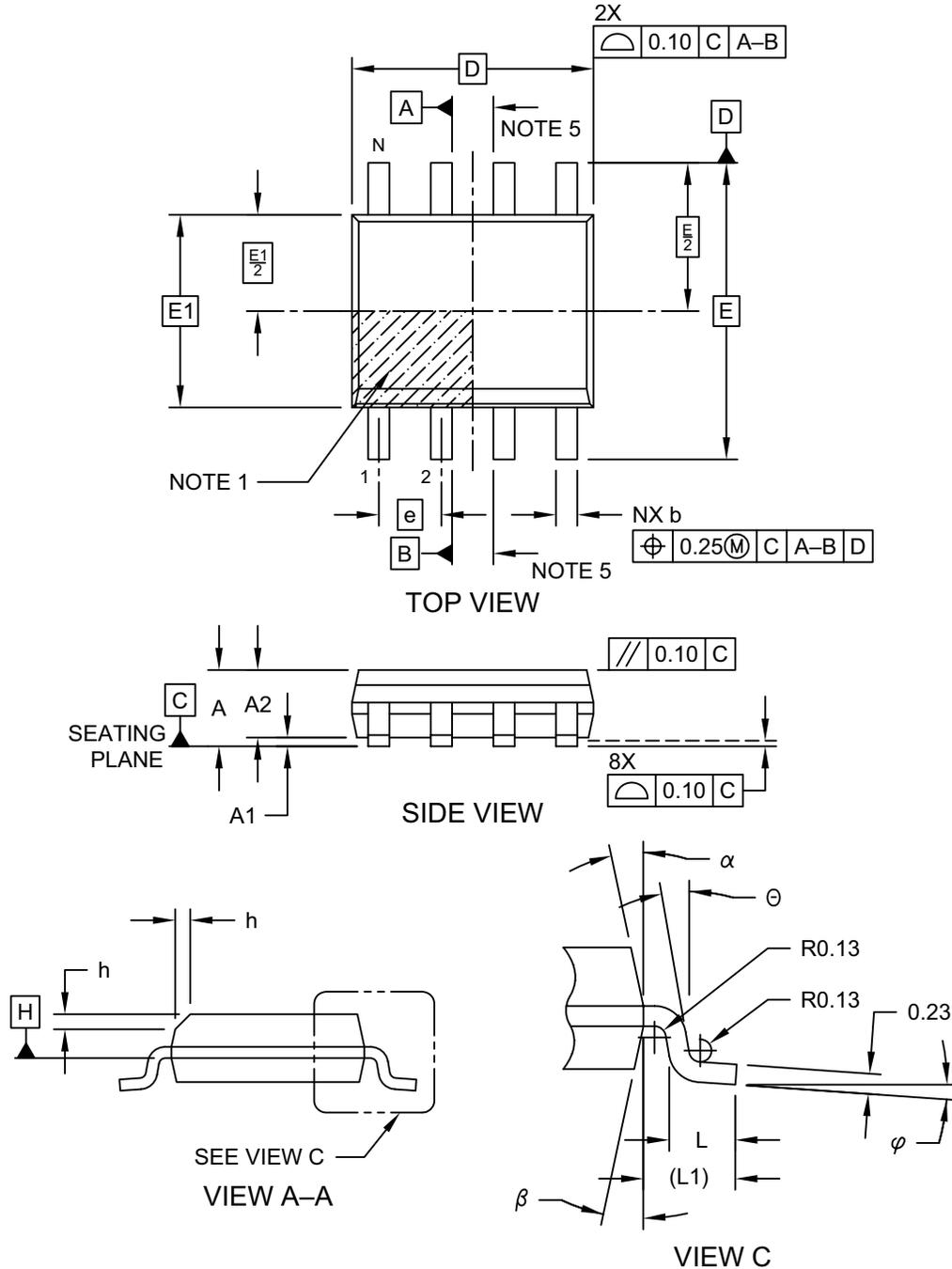
1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. § Significant Characteristic
3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.
4. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-018D Sheet 2 of 2

8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm (.150 In.) Body [SOIC]

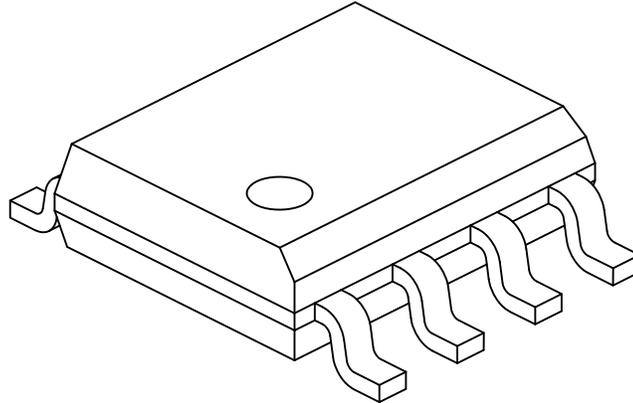
Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing No. C04-057-SN Rev D Sheet 1 of 2

8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm (.150 In.) Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



| Dimension Limits | Units | MILLIMETERS | | |
|--------------------------|-----------|-------------|-----|------|
| | | MIN | NOM | MAX |
| Number of Pins | N | 8 | | |
| Pitch | e | 1.27 BSC | | |
| Overall Height | A | - | - | 1.75 |
| Molded Package Thickness | A2 | 1.25 | - | - |
| Standoff § | A1 | 0.10 | - | 0.25 |
| Overall Width | E | 6.00 BSC | | |
| Molded Package Width | E1 | 3.90 BSC | | |
| Overall Length | D | 4.90 BSC | | |
| Chamfer (Optional) | h | 0.25 | - | 0.50 |
| Foot Length | L | 0.40 | - | 1.27 |
| Footprint | L1 | 1.04 REF | | |
| Foot Angle | φ | 0° | - | 8° |
| Lead Thickness | c | 0.17 | - | 0.25 |
| Lead Width | b | 0.31 | - | 0.51 |
| Mold Draft Angle Top | α | 5° | - | 15° |
| Mold Draft Angle Bottom | β | 5° | - | 15° |

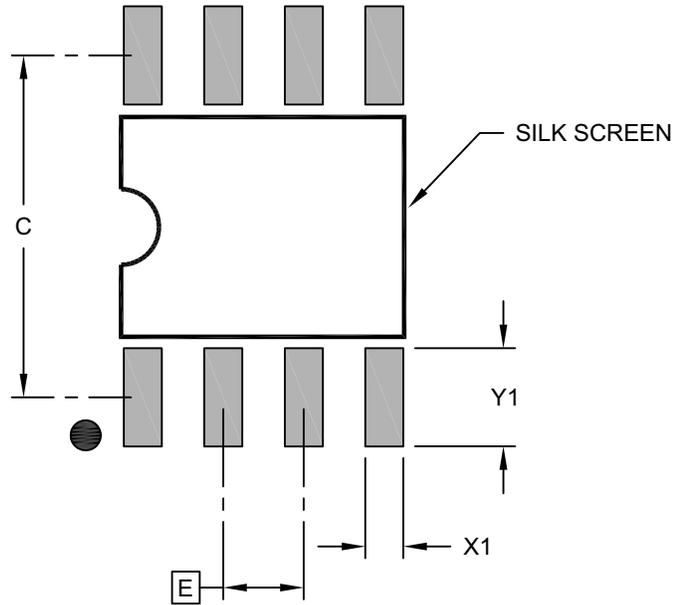
Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. § Significant Characteristic
3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15mm per side.
4. Dimensioning and tolerancing per ASME Y14.5M
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
 - REF: Reference Dimension, usually without tolerance, for information purposes only.
5. Datums A & B to be determined at Datum H.

Microchip Technology Drawing No. C04-057-SN Rev D Sheet 2 of 2

8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

| | | MILLIMETERS | | |
|-------------------------|----|-------------|------|------|
| | | MIN | NOM | MAX |
| Contact Pitch | E | 1.27 BSC | | |
| Contact Pad Spacing | C | | 5.40 | |
| Contact Pad Width (X8) | X1 | | | 0.60 |
| Contact Pad Length (X8) | Y1 | | | 1.55 |

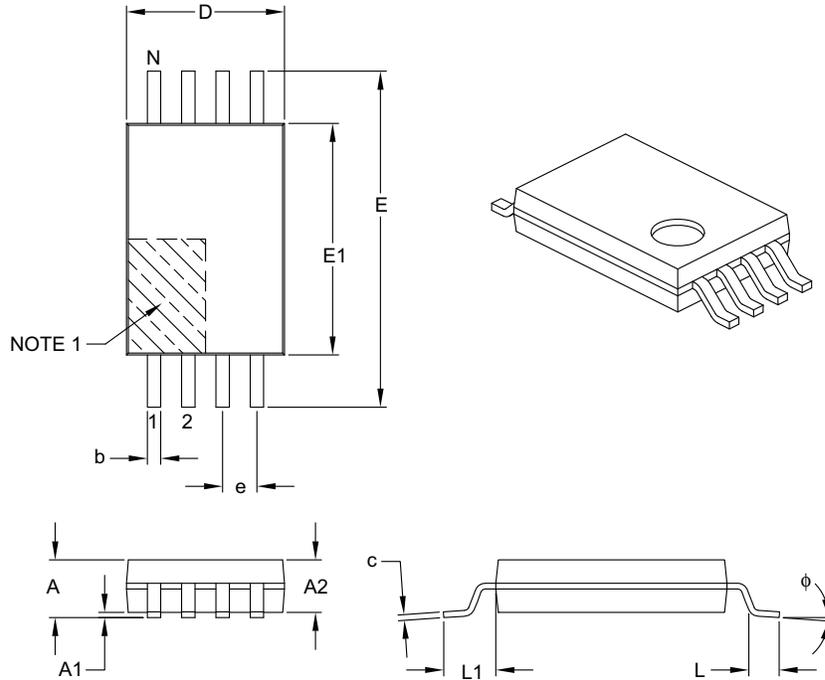
Notes:

1. Dimensioning and tolerancing per ASME Y14.5M
 BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-2057-SN Rev B

8-Lead Plastic Thin Shrink Small Outline (ST) – 4.4 mm Body [TSSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



| | | Units | MILLIMETERS | | |
|--------------------------|--------|-------|-------------|------|------|
| Dimension Limits | | | MIN | NOM | MAX |
| Number of Pins | N | | 8 | | |
| Pitch | e | | 0.65 BSC | | |
| Overall Height | A | – | – | – | 1.20 |
| Molded Package Thickness | A2 | | 0.80 | 1.00 | 1.05 |
| Standoff | A1 | | 0.05 | – | 0.15 |
| Overall Width | E | | 6.40 BSC | | |
| Molded Package Width | E1 | | 4.30 | 4.40 | 4.50 |
| Molded Package Length | D | | 2.90 | 3.00 | 3.10 |
| Foot Length | L | | 0.45 | 0.60 | 0.75 |
| Footprint | L1 | | 1.00 REF | | |
| Foot Angle | ϕ | | 0° | – | 8° |
| Lead Thickness | c | | 0.09 | – | 0.20 |
| Lead Width | b | | 0.19 | – | 0.30 |

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15 mm per side.
3. Dimensioning and tolerancing per ASME Y14.5M.

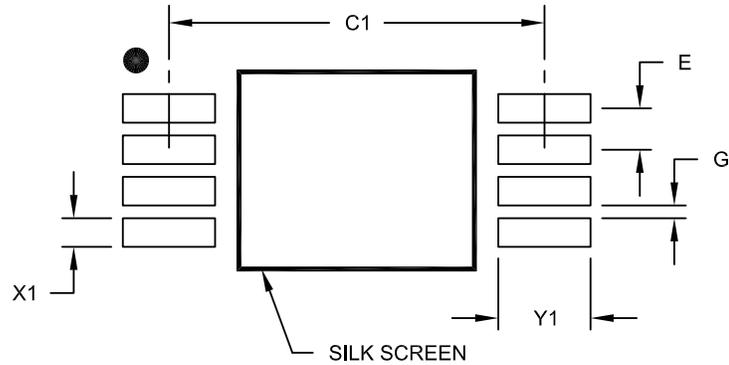
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-086B

8-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

| Dimension Limits | Units | MILLIMETERS | | |
|-------------------------|-------|-------------|-----|------|
| | | MIN | NOM | MAX |
| Contact Pitch | E | 0.65 BSC | | |
| Contact Pad Spacing | C1 | 5.90 | | |
| Contact Pad Width (X8) | X1 | | | 0.45 |
| Contact Pad Length (X8) | Y1 | | | 1.45 |
| Distance Between Pads | G | 0.20 | | |

Notes:

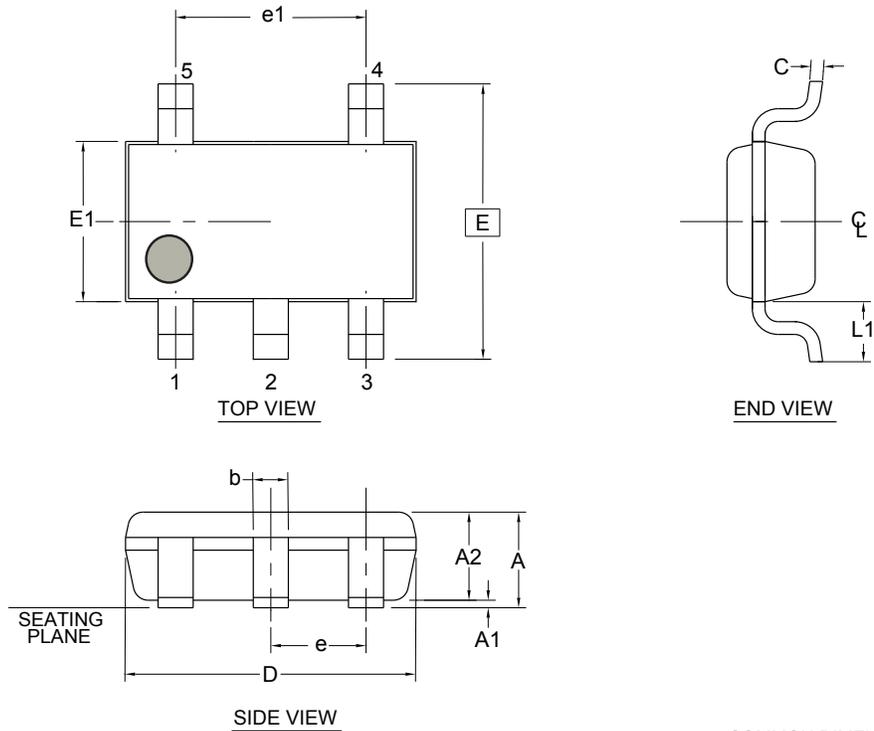
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2086A

AT24C16C

Packaging Information



1. Dimension D does not include mold flash, protrusions or gate burrs. Mold flash, protrusions or gate burrs shall not exceed 0.15 mm per end. Dimension E1 does not include interlead flash or protrusion. Interlead flash or protrusion shall not exceed 0.15 mm per side.
2. The package top may be smaller than the package bottom. Dimensions D and E1 are determined at the outermost extremes of the plastic body exclusive of mold flash, tie bar burrs, gate burrs and interlead flash, but including any mismatch between the top and bottom of the plastic body.
3. These dimensions apply to the flat section of the lead between 0.08 mm and 0.15 mm from the lead tip.
4. Dimension "b" does not include dambar protrusion. Allowable dambar protrusion shall be 0.08 mm total in excess of the "b" dimension at maximum material condition. The dambar cannot be located on the lower radius of the foot. Minimum space between protrusion and an adjacent lead shall not be less than 0.07 mm.

This drawing is for general information only. Refer to JEDEC Drawing MO-193, Variation AB for additional information.

COMMON DIMENSIONS
(Unit of Measure = mm)

| SYMBOL | MIN | NOM | MAX | NOTE |
|--------|----------|------|------|------|
| A | — | — | 1.00 | |
| A1 | 0.00 | — | 0.10 | |
| A2 | 0.70 | 0.90 | 1.00 | |
| c | 0.08 | — | 0.20 | 3 |
| D | 2.90 BSC | | | 1,2 |
| E | 2.80 BSC | | | 1,2 |
| E1 | 1.60 BSC | | | 1,2 |
| L1 | 0.60 REF | | | |
| e | 0.95 BSC | | | |
| e1 | 1.90 BSC | | | |
| b | 0.30 | — | 0.50 | 3,4 |

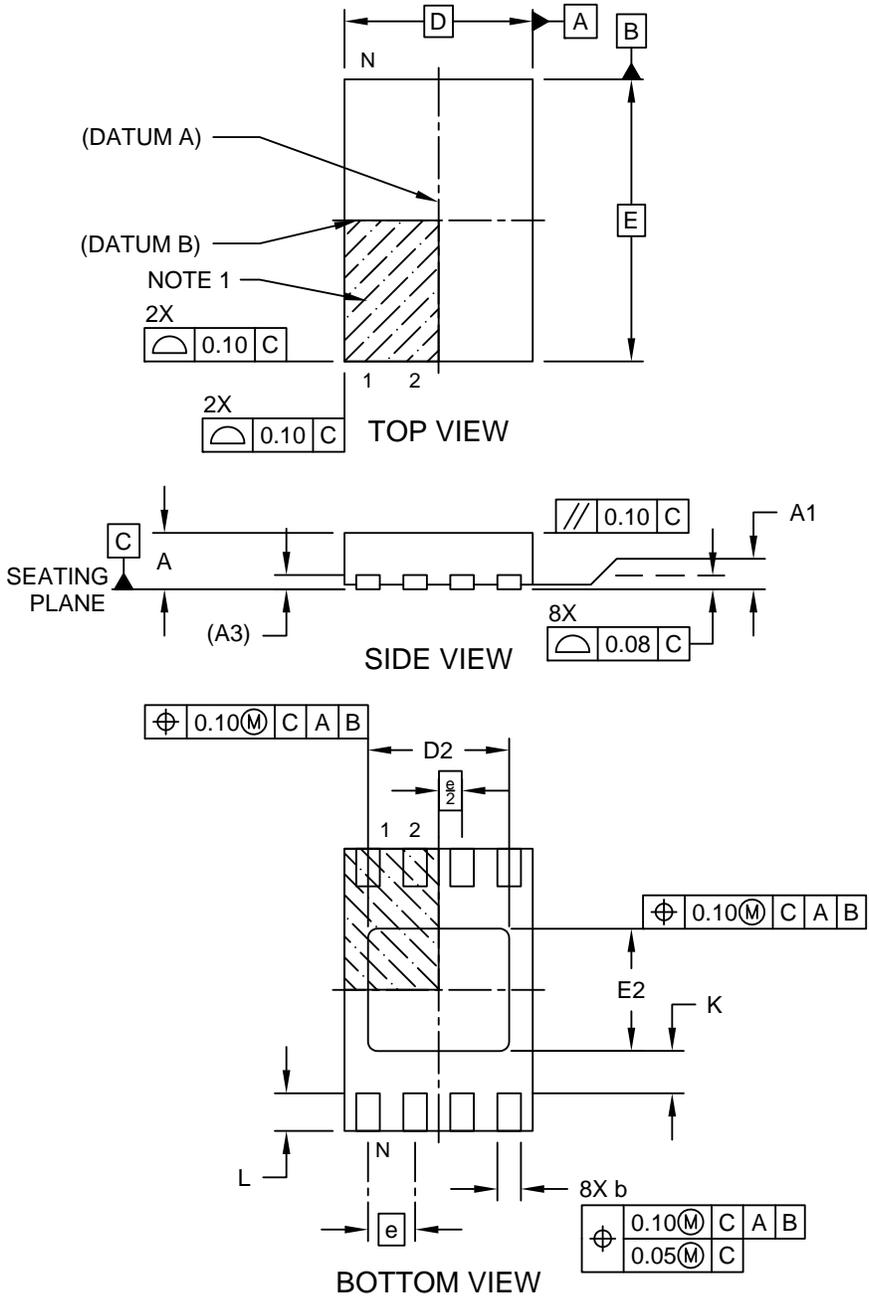
2/2/16

| TITLE | GPC | DRAWING NO. | REV. |
|--|-----|-------------|------|
| 5TS1, 5-lead 1.60mm Body, Plastic Thin Shrink Small Outline Package (Shrink SOT) | TSZ | 5TS1 | E |

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>.

8-Lead Ultra Thin Plastic Dual Flat, No Lead Package (Q4B) - 2x3 mm Body [UDFN]
Atmel Legacy YNZ Package

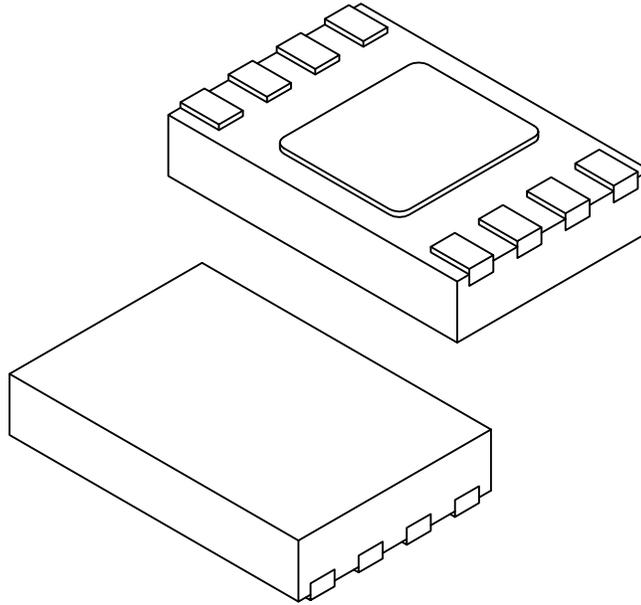
Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing C04-21355-Q4B Rev A Sheet 1 of 2

8-Lead Ultra Thin Plastic Dual Flat, No Lead Package (Q4B) - 2x3 mm Body [UDFN] Atmel Legacy YNZ Package

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



| Dimension Limits | Units | MILLIMETERS | | |
|-------------------------|-------|-------------|------|------|
| | | MIN | NOM | MAX |
| Number of Terminals | N | 8 | | |
| Pitch | e | 0.50 BSC | | |
| Overall Height | A | 0.50 | 0.55 | 0.60 |
| Standoff | A1 | 0.00 | 0.02 | 0.05 |
| Terminal Thickness | A3 | 0.152 REF | | |
| Overall Length | D | 2.00 BSC | | |
| Exposed Pad Length | D2 | 1.40 | 1.50 | 1.60 |
| Overall Width | E | 3.00 BSC | | |
| Exposed Pad Width | E2 | 1.20 | 1.30 | 1.40 |
| Terminal Width | b | 0.18 | 0.25 | 0.30 |
| Terminal Length | L | 0.35 | 0.40 | 0.45 |
| Terminal-to-Exposed-Pad | K | 0.20 | - | - |

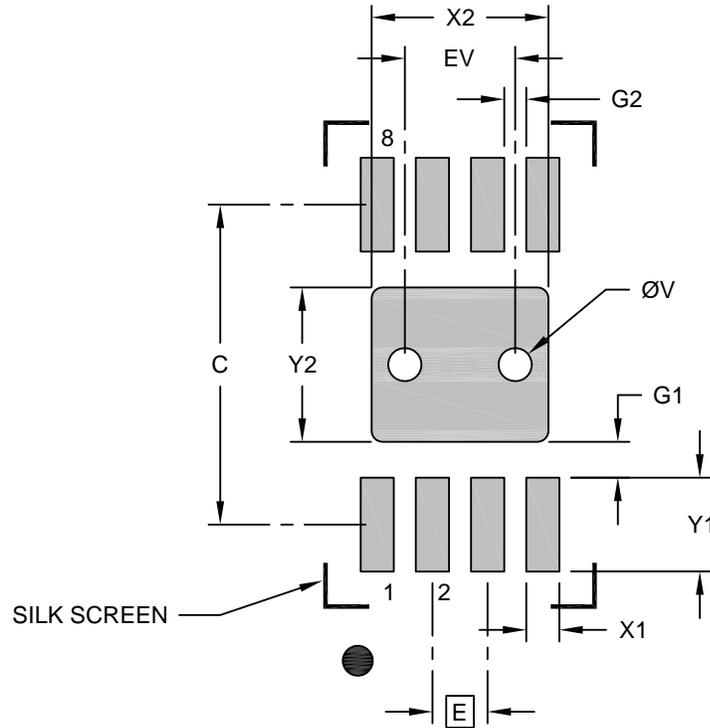
Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Package is saw singulated
3. Dimensioning and tolerancing per ASME Y14.5M
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
 - REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-21355-Q4B Rev A Sheet 2 of 2

**8-Lead Ultra Thin Plastic Dual Flat, No Lead Package (Q4B) - 2x3 mm Body [UDFN]
Atmel Legacy YNZ Package**

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

| Dimension Limits | Units | MILLIMETERS | | |
|---------------------------------|-------|-------------|------|------|
| | | MIN | NOM | MAX |
| Contact Pitch | E | 0.50 BSC | | |
| Optional Center Pad Width | X2 | | | 1.60 |
| Optional Center Pad Length | Y2 | | | 1.40 |
| Contact Pad Spacing | C | | 2.90 | |
| Contact Pad Width (X8) | X1 | | | 0.30 |
| Contact Pad Length (X8) | Y1 | | | 0.85 |
| Contact Pad to Center Pad (X8) | G1 | 0.20 | | |
| Contact Pad to Contact Pad (X6) | G2 | 0.33 | | |
| Thermal Via Diameter | V | | 0.30 | |
| Thermal Via Pitch | EV | | 1.00 | |

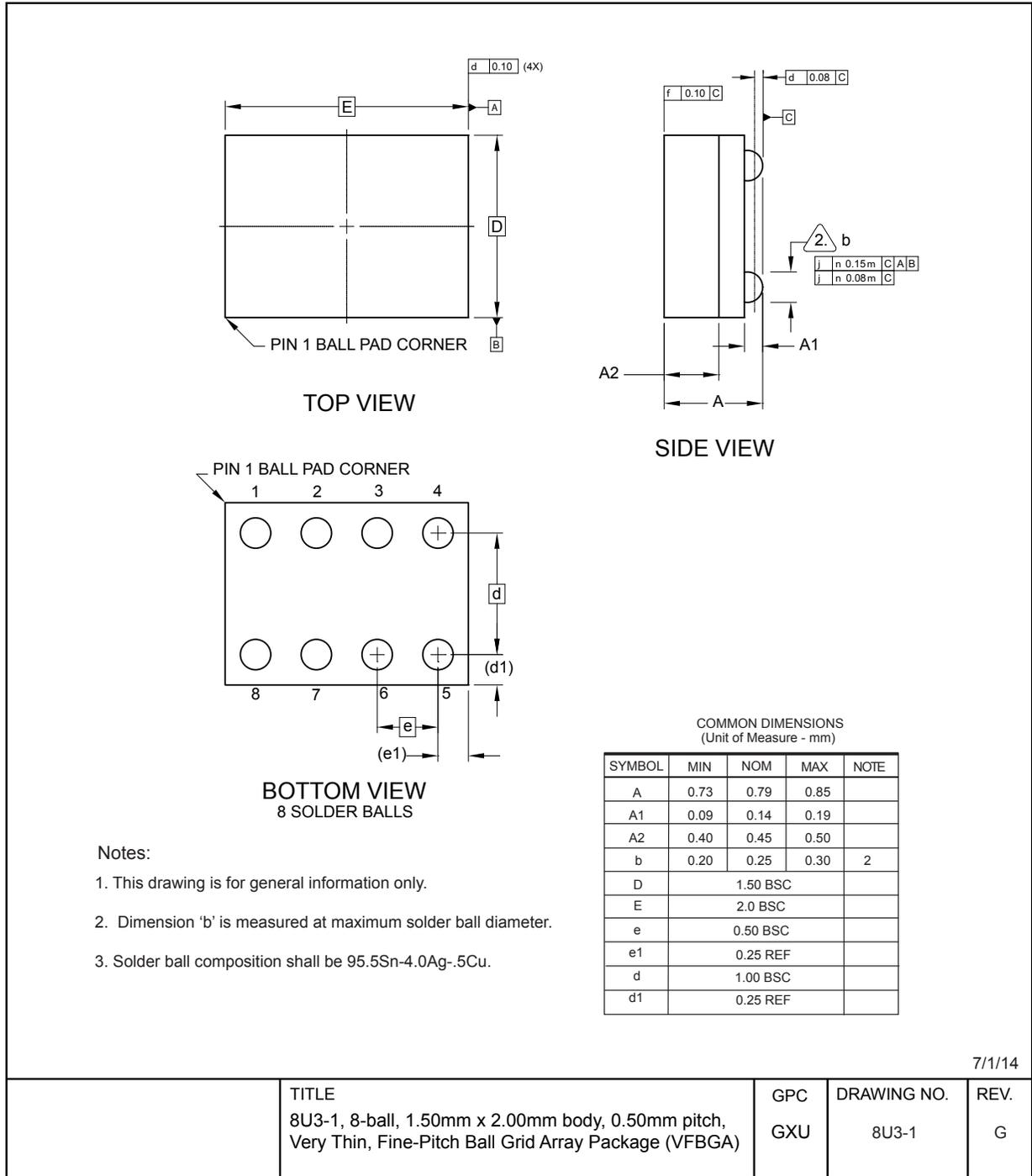
Notes:

1. Dimensioning and tolerancing per ASME Y14.5M
BSC: Basic Dimension. Theoretically exact value shown without tolerances.
2. For best soldering results, thermal vias, if used, should be filled or tented to avoid solder loss during reflow process

Microchip Technology Drawing C04-21355-Q4B Rev A

AT24C16C

Packaging Information

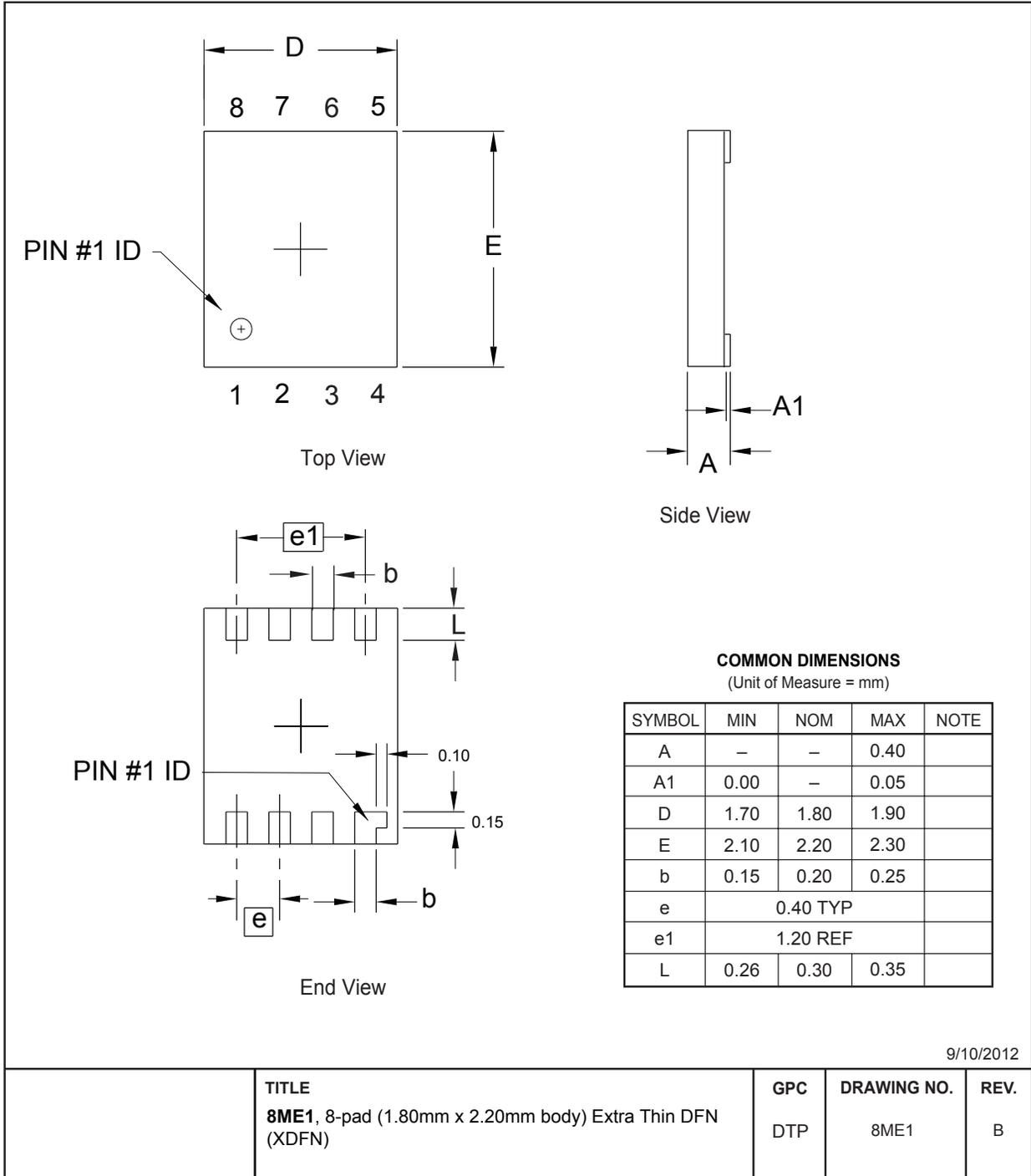


7/1/14

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>.

AT24C16C

Packaging Information



9/10/2012

| | | | | |
|--|---|-------------------|----------------------------|------------------|
| | TITLE 8ME1, 8-pad (1.80mm x 2.20mm body) Extra Thin DFN (XDFN) | GPC DTP | DRAWING NO. 8ME1 | REV. B |
|--|---|-------------------|----------------------------|------------------|

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>.

11. Revision History

Atmel Document 8719 Revision A (September 2010)

Initial release of this document.

Atmel Document 8719 Revision B (July 2013)

Minor grammatical corrections. Updated Atmel logos and template.

Atmel Document 8719 Revision C (January 2015)

Added the UDFN Expanded Quantity Option. Updated the 8X, 8MA2, 8P3, and 8U3-1 package outline drawings, the ordering information section, and the disclaimer page.

Atmel Document 8719 Revision D (December 2016)

Part marking SOT23:

- Moved backside mark (YMXX) to front side line2.
- Added @ = Country of Assembly

Revision A (August 2018)

Updated to the Microchip template. Microchip DS20006051 replaces Atmel document 8719. Corrected t_{LOW} typo from 400 ns to 500 ns. Corrected t_{AA} typo from 550 ns to 450 ns. Updated Part Marking Information. Updated the "Software Reset" section. Added ESD rating. Removed lead finish designation. Updated trace code format in package markings. Added a figure for "System Configuration Using 2-Wire Serial EEPROMs". Updated "Block Diagram" figure. Added POR recommendations section. Updated section content throughout for clarification. Updated the 5TS1 SOT23 and 8U3-1 VFBGA package drawings. Updated the PDIP, SOIC, TSSOP and UDFN package drawings to Microchip format.

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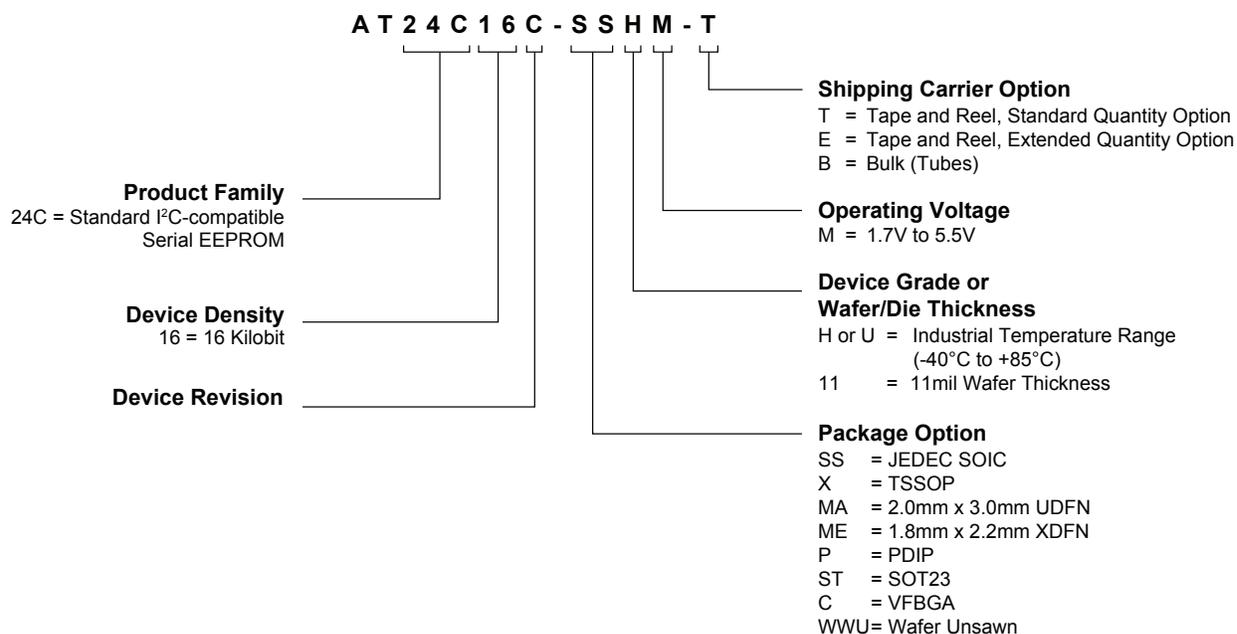
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Examples

| Device | Package | Package Drawing Code | Package Option | Shipping Carrier Option | Device Grade |
|-----------------|---------|----------------------|----------------|-----------------------------|--|
| AT24C16C-PUM | PDIP | P | P | Bulk (Tubes) | Industrial Temperature (-40°C to 85°C) |
| AT24C16C-SSHMT | SOIC | SN | SS | Tape and Reel | |
| AT24C16C-STUM-T | SOT23 | 5TS1 | ST | Tape and Reel | |
| AT24C16C-XHM-B | TSSOP | ST | X | Bulk (Tubes) | |
| AT24C16C-MAHM-T | UDFN | Q4B | MA | Tape and Reel | |
| AT24C16C-MAHM-E | UDFN | Q4B | MA | Extended Qty. Tape and Reel | |
| AT24C16C-CUM-T | VFBGA | 8U3-1 | C | Tape and Reel | |
| AT24C16C-MEHMT | XDFN | 8ME1 | ME | Tape and Reel | |

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