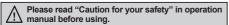
Diameter Ø50mm Shaft Type Incremental Rotary Encoder

Features

- 12-24VDC power supply of line driver output (line-up)
- Suitable for measuring angle, position, revolution, speed, acceleration and distance
- Power supply: 5VDC, 12-24VDC ±5%

Applications

 Various tooling machinery, packing machine and general industrial machinery, etc.



((



Ordering Information (former name: ENB)

E50S	8 -	- 8000 -	- 3	_ N	- 24 -	-
Series	Shaft diameter	Pulse/1Revolution	Output phase	Control output	Power supply	Cable
Diameter Ø50mm, shaft type	Ø8mm	Refer to resolution	2: A, B 3: A, B, Z 4: A, Ā, B, B 6: A, Ā, B, B, Z, Z	Output	5: 5VDC ±5% 24: 12-24VDC ±5%	No mark: Axial cable type C: Axial cable connector type CR: Axial connector type CS: Radial connector type

Specifications

Item			Diameter Ø50mm shaft type of incremental rotary encoder				
Resolution (P/R) ^{×1}		×1	*1, *2 ,*5, 10, 12, 15, 20, 23, 25, 30, 35, 40, 45, 50, 60, 75, 100, 120, 125, 150, 192, 200, 240, 250, 256, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1500, 1800, 2000, 2048, 2500, 3000, 3600, 4000, 5000, 6000, 8000				
	Output phase		A, B, Z phase (line driver: A, \overline{A} , B, \overline{B} , Z, \overline{Z} phase)				
_	Phase difference of output		Output between A and B phase: $\frac{T}{4} \pm \frac{T}{8}$ (T=1 cycle of A phase)				
	Control output	Totem pole output	[Low] - Load current: Max. 30mA, Residual voltage: Max. 0.4VDC [High] - Load current: Max. 10mA, Output voltage (power voltage 5VDC): Min. (power voltage-2.0)VDC,				
		NPN open collector output	Load current: Max. 30mA, Residual voltage: Max. 0.4VDC				
		Voltage output	Load current: Max. 10mA, Residual voltage: Max. 0.4VDC				
		Line driver output	[Low] - Load current: Max. 20mA, Residual: Max. 0.5VDC [High] - Load current: Max20mA, Output voltage (power voltage 5VDC): Min. (power voltage-2.5)VDC, Output voltage (power voltage 12-24VDC): Min. (power voltage-3.0)VDC				
eci e	D	Totem pole output					
Sp.	Response time		Max. 1μs (cable length: 2m, I sink = 20mA)				
	(rise/fall)	Voltage output					
[,	Line driver output	Max. 0.5μs (cable length: 2m, I sink = 20mA)				
	Max. Response frequency		300kHz				
	Power sup	ply	• 5VDC ±5% (ripple P-P: Max. 5%) • 12-24VDC ±5% (ripple P-P: Max. 5%)				
	Current co	nsumption	Max. 80mA (disconnection of the load), Line driver output: Max. 50mA (disconnection of the load)				
	Insulation	resistance	Over. 100MΩ (at 500VDC megger between all terminals and case)				
	Dielectric strength		750VAC 50/60Hz for 1 minute (between all terminals and case)				
	Connection		Axial cable type, Axial cable connector type, Axial/Radial connector type				
<u>ال</u> ا	Starting to	rque	Max. 70gf·cm (0.007N·m) ^{*2} , Max. 800gf·cm (0.078N·m) ^{*3}				
agi ji	Moment of inertia		Max. 80g·cm² (8×10 ⁻⁶ kg·m²) ^{×2} , Max. 400g·cm² (4×10 ⁻⁵ kg·m²) ^{×3}				
Mechanical specification	Shaft loading		Radial: Max. 10kgf, Thrust: Max. 2.5kgf				
≅ g	Max. allowable revolution*4		5,000rpm				
Vibration			1.5mm amplitude at frequency of 10 to 55Hz in each X, Y, Z direction for 2 hours				
			Approx. Max. 75G				
		Ambient temperature	-10 to 70°C, Storage: -25 to 85°C				
∟nvir	onment	Ambient humidity	35 to 85%RH, Storage: 35 to 90%RH				
Protection structure			Axial cable type, Axial cable connector type: IP50 (IEC standards) ^{※5} , Axial/Radial connector type: IP65 (IEC standards)				
Cable			Ø5mm, 5-wire (line driver output: 8-wire), 2m, Shield cable (AWG 24, core diameter: Ø1mm, number of cores: 40, insulator out diameter: Ø1mm)				
Accessory			Ø8mm coupling, Bracket				
Approval			(€ (except for line driver output)				
Weight ^{⋇6}			Approx. 363g (approx. 275g), Axial/Radial connector type: Approx. 268g (approx. 180g)				

- X1: *** pulse is only for A, B phase (line driver output is for A, Ā, B, B̄ phase). Not indicated resolutions are customizable.
- X2: This value is for Axial cable type, Axial cable connector type (protection structure: IP50).
- **3: This value is for Axial cable type, Axial cable connector type (protection structure: IP64), Axial/Radial connector type (protection structure: IP65).
- **4: Make sure that Max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

[Max. response resolution (rpm) = $\frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec }]$

- %5: In case of axial cable type, axial cable connector type, they are available to order the option protection structure IP64.
- *6: The weight includes packaging. The weight in parentheses is for unit only.

 *Environment resistance is rated at no freezing or condensation

(A) Photoelectric Sensors

(B) Fiber Optic

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(G) Connectors/ Connector Cables/ Sensor Distributior Boxes/ Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J) Counters

imers

(M) Tacho / Speed / Pulse

Meters

(N)

Display
Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors

& Drivers & Controllers (R)

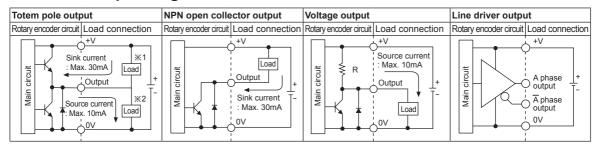
Graphic/ Logic Panels

Field Network Devices

(T) Software

F-17

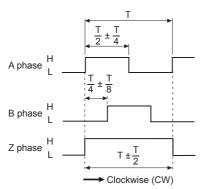
Control Output Diagram



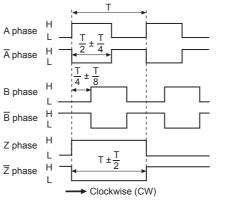
- All output circuits of A, B, Z phase are same. (line driver output is A, A, B, B, Z, Z)
- Totem pole output type can be used for NPN open collector type(%1) or voltage output type(%2).

Output Waveforms

 Totem pole output / NPN open collector output / Voltage output



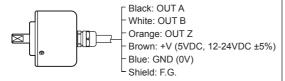
Line driver output



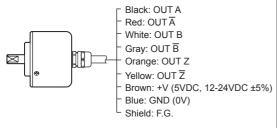


Connections

- Axial cable type
- Totem pole output / NPN open collector output / Voltage output



• Line driver output



- XUnused wires must be insulated.

- Axial cable connector type /
 Axial/Radial connector type
- Totem pole output
 NPN open collector output
 Voltage output
- Line driver output





	- 000000	v -				
• NPN o	pole outpopen collection	ut ctor output	Line driver output			
Pin No.	Function	Cable color	Pin No.	Function	Cable color	
1	OUT A	Black	1	OUTA	Black	
2	OUT B	White	2	OUTĀ	Red	
3	OUT Z	Orange	3	+V	Brown	
4	+V	Brown	4	GND	Blue	
5	GND	Blue	5	OUT B	White	
6	F.G.	Shield	6	OUT B	Gray	
			7	OUT Z	Orange	
			8	OUT Z	Yellow	
			9	F.G.	Shield	

XF.G. (field ground): It should be grounded separately.

Incremental Ø50mm Shaft Type

Dimensions



(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

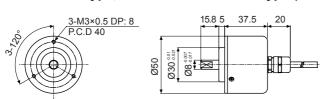
(I) SSRs / Power Controllers

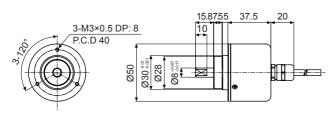
(J) Counters

(P) Switching Mode Power Supplies (Q) Stepper Motors

& Drivers & Controllers

(R) Graphic/ Logic Panels

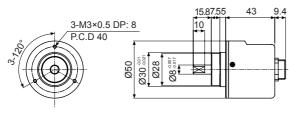




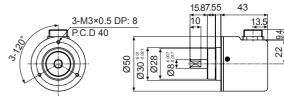
Cable for Axial cable type Ø5mm, 5-wire (line driver output: 8-wire), 2000mm, Shield cable Cable for Axial cable connector type Ø5mm, 5-wire (line driver output: 8-wire), 250mm, Shield cable

XConnector cable is sold separately and refer to page G-10 for specifications.

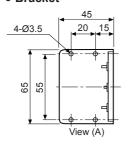
Axial connector type

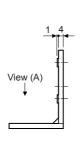


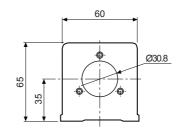
Radial connector type



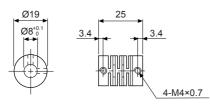
Bracket







• Coupling (E50S)



- Parallel misalignment: Max. 0.25mm
- Angular misalignment: Max. 5°
- End-play: Max. 0.5mm

*When mounting the coupling to the encoder shaft, if there is combined misalignment (parallel, angular misalignment) between rotating encoder shaft and mate shaft, it may cause encoder and coupling's life cycle to shorten.

- XDo not load overweight on the shaft.
- XFor parallel misalignment, angular misalignment, end-play terms, refer to page F-71.
- XFor flexible coupling (ERB series) information, refer to page F-64.

F-19 **Autonics**

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